

# Geometric Entropy Minimization

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# Acknowledgements

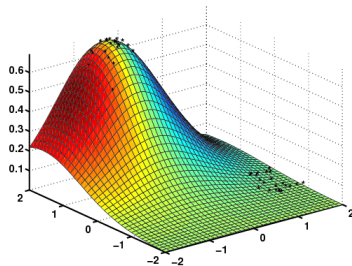
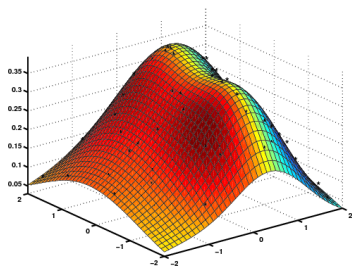
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- 1 Motivation
- 2 Entropy minimization
- 3 Euclidean graphs
- 4 Dimension estimation
- 5 Anomaly detection
- 6 Conclusions

# Outline

- 1 Motivation
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# Feature distribution supported on a smooth surface



## Objective

Estimate subspace  $\mathcal{S}$  along with its dimension  $d \leq D$  and infer properties of sample distribution  $f(y)$ ,  $f(y) = 0$  for  $y \notin \mathcal{S}$ .

# Unifying theme

- Inferring complexity from data
- Estimating dimension of a dataset or a distribution
- Performing dimensionality reduction for visualization
- Capturing differences/anomalies between distributions

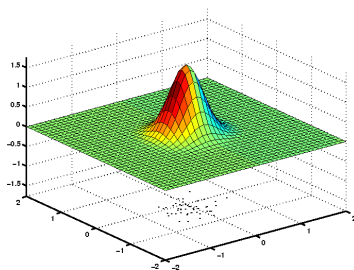
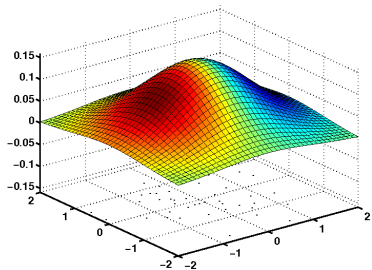
# Unifying theme

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**Entropy and relative entropy are key tools**

$$H(f) = \frac{1}{1-\alpha} \int_S f^\alpha(x) dx, \quad D(f||g) = \frac{1}{\alpha-1} \int_S \left( \frac{g(x)}{f(x)} \right)^\alpha f(x) dx$$

# Feature Densities on $\mathbb{R}^2$



High entropy and low entropy feature densities



# Generalized (Rényi) Entropy

Rényi entropy for a discrete r.v.  $X$  with pmf  $p(x)$  (here  $\alpha > 0$ )

$$H_\alpha(X) = H_\alpha(p) = \frac{1}{1-\alpha} \log \sum_{x \in \mathcal{X}} p^\alpha(x) = \frac{1}{1-\alpha} \log E [p^{\alpha-1}(X)]$$

Rényi entropy for a continuous r.v.  $X$  with pdf  $f(x)$

$$H_\alpha(X) = H_\alpha(f) = \frac{1}{1-\alpha} \log \int f^\alpha(x) dx = \frac{1}{1-\alpha} \log E [f^{\alpha-1}(X)]$$

Conditional Rényi entropy

$$H_\alpha(X|Y) = \int f_Y(y) \underbrace{\left( \frac{1}{1-\alpha} \log \int f_{X|Y}^\alpha(x|y) dx \right)}_{H_\alpha(X|Y=y)} dy$$

# Extremal properties of Rényi entropy

- If  $X$  is discrete with finite alphabet  $\mathcal{X} = \{x_1, \dots, x_Q\}$

$$H_\alpha(X) \leq \log|\mathcal{X}| = \log Q, \quad " = " \text{ iff } p(x_i) = \frac{1}{Q} \quad \forall i$$

- If  $X$  is continuous on  $\mathcal{X} = \mathbb{R}$  with finite variance  $\text{var}(X) = E[X^2] - E^2[X]$  then  $H(X)$  is maximized by a student-t density w 1 degree of freedom and identical variance.
- For  $X$  in  $\mathbb{R}^d$  with given finite covariance matrix  $\Sigma$  Rényi entropy is maximized by multivariate Student-t density with given covariance parameter (Vignat et al [22]).

# Limiting forms of Rényi entropy

- Shannon entropy limit

$$\lim_{\alpha \rightarrow 1} H_\alpha(X) = H(X) = - \int f(x) \log f(x) dx$$

- Equally likely entropy limit

$$\lim_{\alpha \rightarrow 0} H_\alpha(X) = \log Q$$

- Rarest outcome limit

$$\lim_{\alpha \rightarrow \infty} H_\alpha(X) = \log \frac{1}{\min p(x)}$$

# Rényi entropy and lossless coding

- Complexity of an ensemble  $X$  = average number of bits required to optimally encode  $X$ .
- Shannon entropy  $H(X)$  is optimal avg code length that minimizes redundancy
- Rényi entropy  $H_\alpha(X)$  is optimal avg exponentiated code length that minimizes redundancy
- Rényi entropy  $H_\alpha(X)$  increasingly sensitive to tail behavior of  $f(x)$  as  $\alpha$  decreases to zero.

# Some background on Rényi entropy

- 1948 - **C. Shannon** Shannon's entropy measure published [21]
- 1961 - **A. Rényi** Rényi's  $\alpha$ -entropies published [20]
- 1966 - **L.L. Campbell** SE and RE related by source coding arguments [1]
- 1967 - **J. Havra** Rényi's entropy applied to classification [9]
- 1989 - **A. Mokkadem** RE used for Shannon entropy approximation [17]
- 1992 - **W. Williams** RE applied to time frequency distributions [25]
- 1994 - **B. Frieden** RE applied to signal reconstruction [7]
- 1998 - **AH** RE applied to outlier detection [13]
- 1998 - **D. Xu** RE applied to ICA [26]
- 2001 - **E. Gockay** RE applied to clustering [8]
- 2002 - **Erdogmus** RE applied to blind deconvolution [6]
- 2002 - **H. Krim** RE applied to image registration [10]
- 2003 - **C. Kreucher** RE applied to sensor management [15]
- 2004 - **S. Vinga** RE applied to DNA sequence analysis [23]
- 2004 - **J. Costa** RE applied to dimension estimation [4]
- 2005 - **H. Neemuchwala** RE applied to image retrieval [18]
- 2006 - **K. Carter** RE applied to anomaly detection [3]

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# Entropy minimization

## Statistical parameter estimation

Define:  $Y = [y_1, \dots, y_p]$  a set of latent variables (model) and  $X = [x_1, \dots, x_n]$ ,  $x \in \mathbb{R}^D$ , data generated from model  $Y$ .

Define: empirical entropy  $\hat{H}(X) = \frac{1}{n} \sum_{i=1}^n \phi(f(X_i|Y))$

$$\phi(u) = \begin{cases} u^{\alpha-1}/(1-\alpha), & \text{Rényi} \\ \log u, & \text{Shannon} \end{cases}$$

- Maximum likelihood estimator ( $p$  known):  
 $\hat{Y} = \min_y \hat{H}(X|Y = y)$ .
- Minimum description length (MDL) estimator ( $p$  unknown):  
 $\hat{p}_{MDL} = \min_p \hat{H}(X, Y)$  (consistent as  $n \rightarrow \infty$ ).

# Entropy minimization

## Non-parametric inference and learning

### Image registration and pattern matching (Viola [24])

Estimate transformation  $\mathcal{T}$  from pair of images  $\{X, Y\}$ ,

$$Y = \mathcal{T}(X) + \varepsilon.$$

$$\hat{\mathcal{T}} = \operatorname{argmin}_{\mathcal{T}} H(X, Y)$$



# Entropy minimization

## Non-parametric inference and learning

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### Anomaly detection (AH [14])

Test deviation of sample not from nominal density  $f = f_0$

$$X_n \notin \operatorname{argmin}_{\mathcal{B}: P(\mathcal{B}) \geq 1-\alpha} H_0(X|X \in \mathcal{B}) \int_{\mathcal{B}} f_0^\alpha(x) dx$$

# Entropy minimization

## Non-parametric inference and learning

### Image registration and pattern matching (Viola [24])

Estimate transformation  $\mathcal{T}$  from pair of images  $\{X, Y\}$ ,

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$$\hat{\mathcal{T}} = \operatorname{argmin}_{\mathcal{T}} H(X, Y)$$

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Test deviation of sample not from nominal density  $f = f_o$

$$X_n \notin \operatorname{argmin}_{\mathcal{B}: P(\mathcal{B}) \geq 1-\alpha} H_0(X|X \in \mathcal{B}) \int_{\mathcal{B}} f_0^\alpha(x) dx$$

### Local dimension estimation (Costa [4])

Estimate intrinsic dimension  $d_z$  of  $\mathcal{S}$  in vicinity of a point  $x = z$

$$\hat{d}_z = \lim_{r \rightarrow 0} \frac{dH(X|X \in B(z, r))}{d(\log r)}$$

# Dimension estimation and entropy minimization

Consider growth rate of entropy over small expanding neighborhood



Linear equation  $\mathbf{L} = d\mathbf{R} + c\mathbf{1}$  in intrinsic dimension  $d \leq D$ :

$$\begin{bmatrix} \log \int_{B(x_0, r_0)} \phi(f(x)) dx \\ \log \int_{B(x_0, r_1)} \phi(f(x)) dx \end{bmatrix} = d \begin{bmatrix} \log r_0 \\ \log r_1 \end{bmatrix} + \begin{bmatrix} c(x_0) \\ c(x_0) \end{bmatrix} + \begin{bmatrix} \varepsilon_0 \\ \varepsilon_1 \end{bmatrix}$$

# Dimension estimation and entropy minimization

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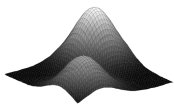
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$$\hat{d} = \operatorname{argmin}_m \min_c \|\mathbf{L} - m\mathbf{R} - c\mathbf{1}\|_2$$

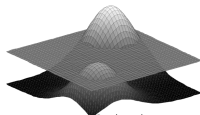
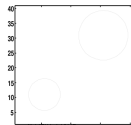
# Anomaly detection and entropy minimization

level set = minimum entropy set of nominal density  $f_o(x)$



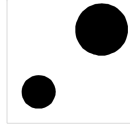
- Density function  $f(x)$
- Level sets

$$C(l) = \{x : f(x) = l\}$$



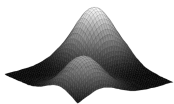
- Cutting plane
- Epigraph sets

$$S(l) = \{x : f(x) \geq l\}$$



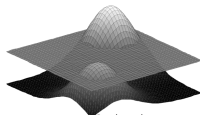
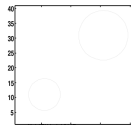
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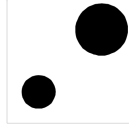
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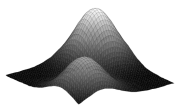
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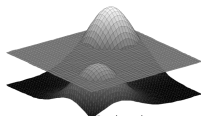
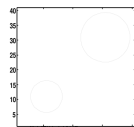
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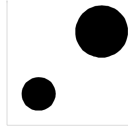
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- Cutting plane
- Epigraph sets

$$S(l) = \{x : f(x) \geq l\}$$



p-value:  $p_v(X_i) = \min_{\alpha > 0} P_o(X_i \notin S_{1-\alpha})$

$$P_o(X_i \notin S_{1-\alpha}) = 1 - \int_{S_{1-\alpha}} f_o(x) dx$$

$$S_{1-\alpha} = \operatorname{argmin}_{\mathcal{B}: P_o(\mathcal{B}) \geq 1-\alpha} \int_{\mathcal{B}} f_o^\alpha(x) dx$$

# Entropy estimation

Let  $h(f)$  be defined as a functional of  $f$  for given function  $\phi$

$$h(f) = \int \phi(f(x)) dx$$

Example,  $\phi(f) = f^\alpha / (1 - \alpha)$

$$h(f) = \frac{1}{1 - \alpha} \int f^\alpha(x) dx$$

Question: how to estimate  $h$  from empirical data?

Two methods

- Explicit density plug-in estimator

$$\hat{h} = h(\hat{f}), \quad \hat{f} = \hat{f}(X_1, \dots, X_n)$$

- Estimation without explicit plug-in

$$\hat{h} = \hat{h}(X_1, \dots, X_n)$$



# Density plug-in estimates

## Drawbacks

Drawbacks of density estimation methods for entropy estimation

- Optimal kernel bandwidth selection  $\sigma = O(n^{-1/d})$  is difficult
- Datastructures for histograms are impractical in very high dimensions
- MSE convergence rate becomes logarithmic in  $n$  for large  $d$

$$n^{-1/d} = \frac{d}{d + \log n} + O(1/d)$$

- May have few samples (fewer than dimensions)
- Density estimation in very high dimensions is fraught with difficulties

# Entropy estimation without density estimation

Examples of entropy estimation methods not requiring density estimation

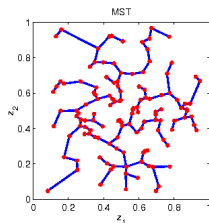
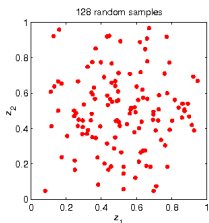
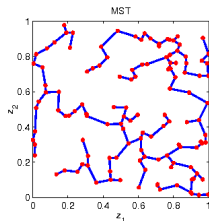
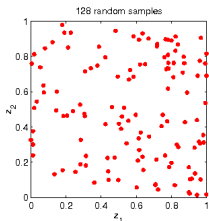
- Data compression (LZ, CWT) entropy estimators (Kontoyanis 1998)
- kNN estimators (Leonenko 2008) [16]
- Entropic graph estimators (AH 1998) [14]

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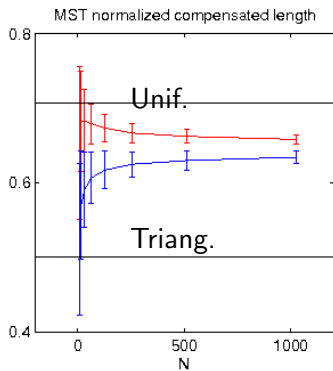
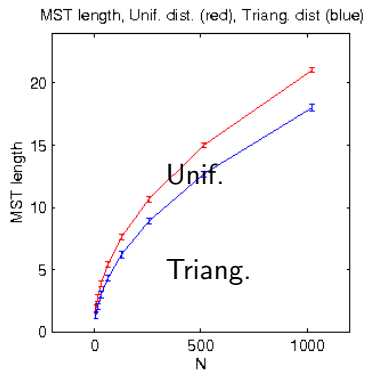
# Euclidean graphs

Minimal spanning tree (MST) for uniform and triangular densities over  $\mathbb{R}^D$



# Rényi entropy and combinatorial optimization

## MST total weight curves



**Figure:** MST and log MST total weight as function of the number of samples.

# Strong convergence result

## BHH convergence theorem

Let  $e_{ij} = \|x_i - x_j\|$  and let  $L_n$  be weighted edge length

$$L_n = \sum e_{ij}^\gamma, \quad \gamma \in (0, d)$$

Steele's (1988) version of the Beardwood, Halton, Hammersley (1959) Theorem

*Let  $\{X_i\}_{i=1}^n$  be an i.i.d sequence of random variables with p.d.f.  $f(x)$  having compact support in  $\mathbb{R}^d$ ,  $d > \gamma > 0$ .*

*Then the weight of the MST satisfies*

$$L_n/n^{(d-\gamma)/d} \rightarrow \beta_{d,L} \int_{\mathbb{R}^d} f^{(d-\gamma)/d}(x) dx \quad (\text{w.p.1})$$

This extends to kNN, TSP, Steiner tree, minimal matching graph

# Strong convergence result

Rényi entropy and BHH convergence theorem

Or, letting  $\alpha = (d - \gamma)/d$

$$\lim_{n \rightarrow \infty} L_\gamma(\mathcal{X}_n)/n^\alpha = \beta_{d,L} \exp((1 - \alpha)H_\alpha(f)), \quad (a.s.)$$

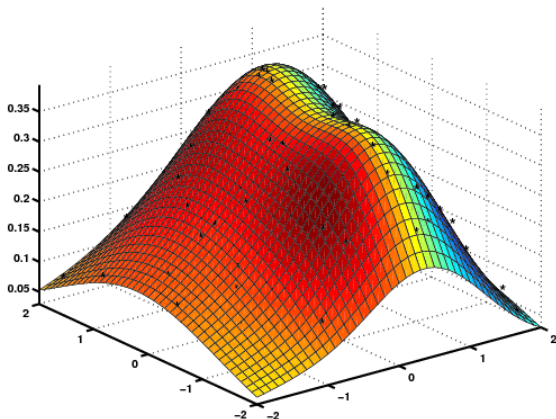
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# Dimension estimation

Data collected in extrinsic dimension  $D$  but supported on a set  $\mathcal{S} = \{x : f(x) > 0\}$  of dimension  $d < D$



Question: how to estimate intrinsic dimension  $d$  of  $X$ ?

# Extended BHH theorem

## BHH for points on a Riemannian manifold

**Theorem:** (Costa [4],[5]) Let  $(\mathcal{S}, g)$  be a compact smooth Riemann  $d$ -dimensional manifold in  $\mathbb{R}^D$ . Suppose  $\mathcal{X}_n = \{X_1, \dots, X_n\}$  is a random sample on  $\mathcal{S}$  with bounded density  $f$  relative to  $\mu_g$  and  $d \geq 2$ ,  $1 \leq \gamma < d$ . Then

$$\lim_{n \rightarrow \infty} \frac{L_\gamma(\mathcal{X}_n)}{n^\alpha} = \beta_{d,L} \int_{\mathcal{S}} f^\alpha(x) d\mu_g(dx)$$

where  $\alpha = (d - \gamma)/d$ .

Furthermore, the mean  $E[L_\gamma(\mathcal{X}_n)]/n^\alpha$  converges to the same limit.

# Dimension estimation

Implication of extended BHH theorem:

**Thm: (Costa [5])**

$$L_n/n^\alpha \rightarrow \beta_{d,L} \int_{\mathcal{S}} f^\alpha(x) d\mu_g(x) = \beta_{d,L} H_\alpha(X) \quad (\text{w.p.1})$$

$$\alpha = (d - \gamma)/d$$

**Another representation** For finite  $n$

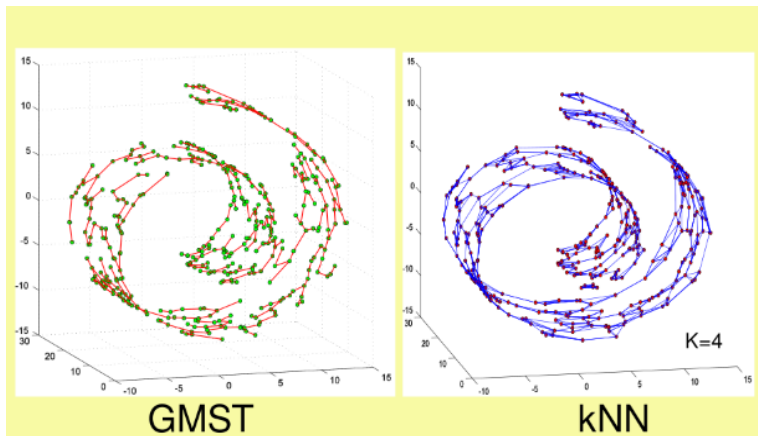
$$\log L_n = \alpha \log n + (1 - \alpha) H_\alpha(X) + \log \beta_{d,L} + \varepsilon(n)$$

where  $\varepsilon(n) \rightarrow 0$  w.p.1.

**Key observation:** Rate of growth of  $L_n$  in  $n$  provides a consistent estimate of  $\alpha$  that can be used to estimate intrinsic dimension  $d$  of  $\mathcal{S}$ .

# Dimension estimation

## Synthetic example

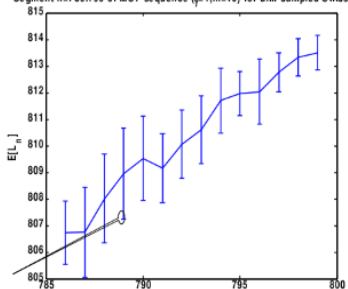


# Dimension estimation

## Synthetic example

### Growth rate estimates of GMST

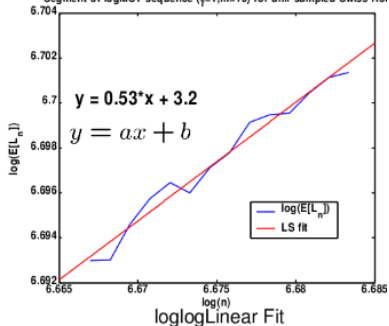
Segment n=786:799 of MST sequence ( $\gamma=1, m=10$ ) for unif sampled Swiss Roll



Bootstrap SE bar (83% CI)

$$\hat{d} = \text{round} \left( \underbrace{\frac{\gamma}{1-a}}_{2.1} \right) = 2$$

Segment of logMST sequence ( $\gamma=1, m=10$ ) for unif sampled Swiss Roll



$$\hat{H}_\alpha(f_Y) = \frac{b-\gamma/2 \log \beta_{\hat{d}}}{1-a} = 7.3$$

Truth  $H_\alpha(f_V) = \log(1869) = 7.53$

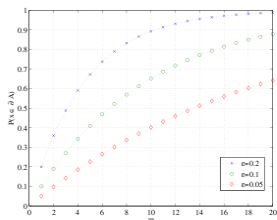
# Dimension estimator bias in high dimensions

Let  $X = [x_1, \dots, x_d]$  be a random vector uniformly distributed in unit cube  $[0, 1]^d$

**Theorem:** for any  $\epsilon > 0$

$$P(\epsilon \leq x_i \leq 1 - \epsilon, \forall i) \leq e^{-2\epsilon d}$$

Thus, as  $d \rightarrow \infty$ ,  $X$  escapes to the “edge” of cube with overwhelming probability - even though  $X$  uniform.



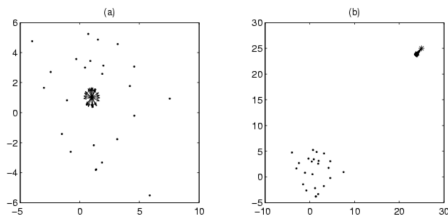
# Dimension estimator bias in high dimensions

## Data Depth

Let  $X_1, \dots, X_n$  be an i.i.d. sample in  $\mathbb{R}^D$

**Definition:** (Vardi 2003) The L1 data depth of a point  $X = X_i$  is

$$D_n(X) = 1 - \max \left( 0, \left\| n^{-1} \sum_{X_i \neq X} \mathbf{e}(X_i - X) \right\| - n^{-1} \sum_{X_i = X} \right)$$



**Figure:** Left: a point “deep” inside data has depth  $\approx 1$ . Right: a outlying point has depth  $\approx 0$  (Vardi 2003)

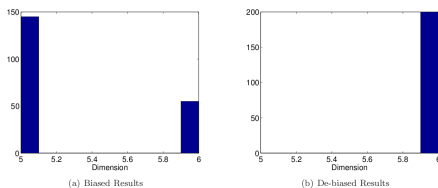
# Dimension estimator bias in high dimensions

## Data Depth Weighting

**Data-depth-weighted dimension estimator:** (Carter 2003 [2])

$$\hat{d} = \frac{\sum_{i=1}^n W_i \hat{d}_i}{\sum_{i=1}^n W_i}$$

$$W_i = \exp(-(1 - D_n(X_i))/\sigma)$$



**Figure:** Histograms of 200 dimension estimates obtained from 3000 i.i.d. uniform random vectors on 6 dimensional unit sphere.



# Dimension estimation

## MNIST Digits

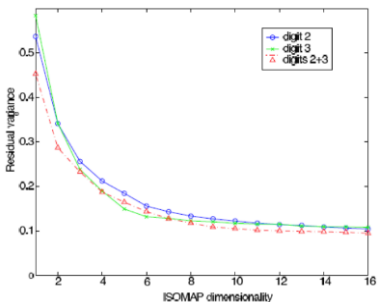


Figure: MNIST digits ( $48 \times 64$ ) and “scree” plot of spectrum

# Dimension estimation

## MNIST Digits

### Local Dimension/Entropy Statistics

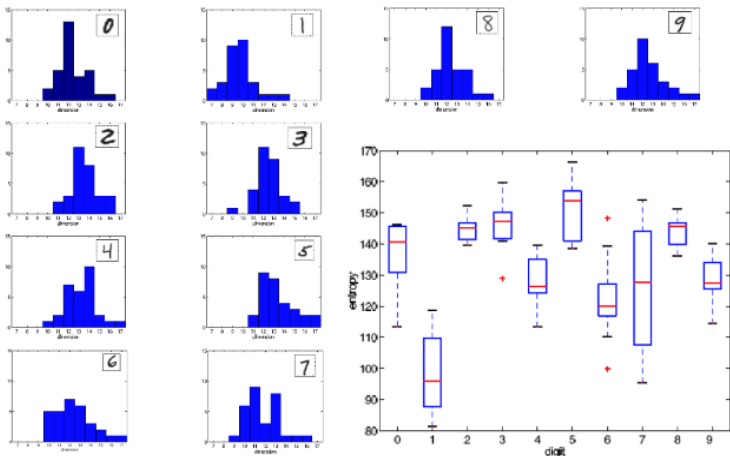


Figure: Hero and Costa [5]

# Dimension estimation

Internet traffic

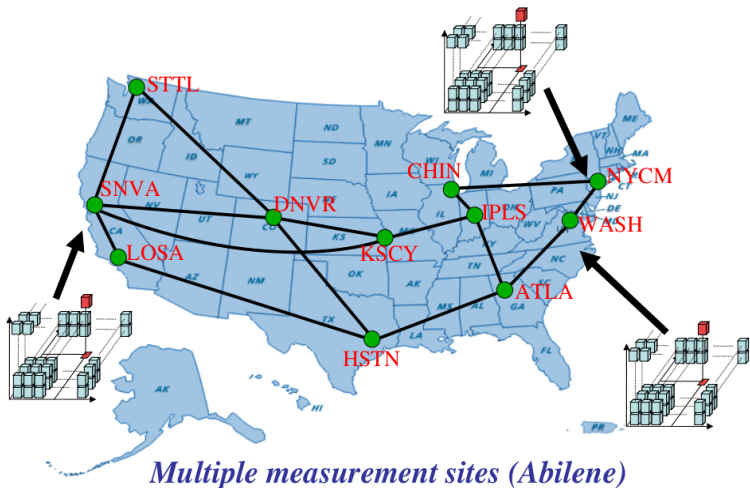
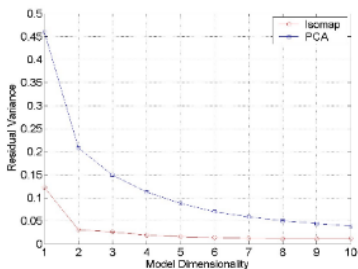


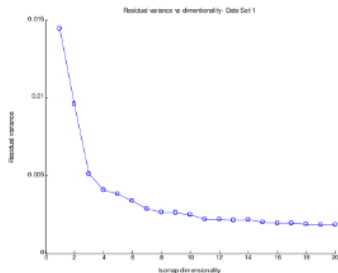
Figure: Patwari and Hero [19]

# Dimension estimation

## Internet traffic scree plot



Residual fitting curves  
for  $11 \times 21 = 231$  dimensional  
Abilene Netflow data set

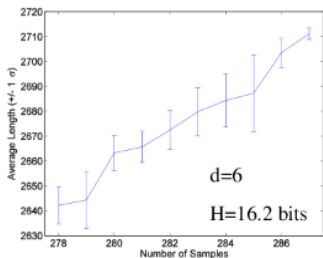


ISOMAP residual curve  
for 40+ dimensional  
Abilene OD link data  
(Lakhina, Crovella, Diot)

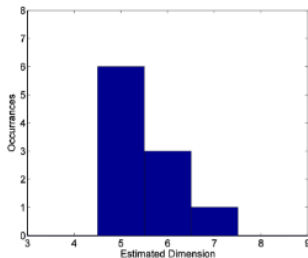
# Dimension estimation

## Global intrinsic dimension of internet traffic

- 11 routers and 21 applications = each sample lives in 231 dimensions
- 24 hour data block divided into 5 min intervals = 288 samples



Mean GMST Length Function

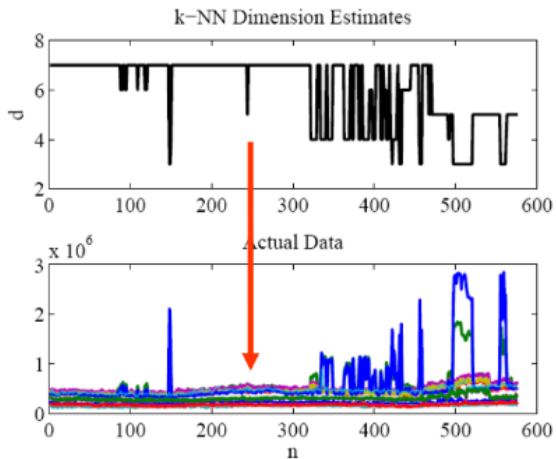


Resampling histogram of  $\hat{d}$

# Dimension estimation

Local dimension scan statistic for internet traffic

Abilene Netflow data (traffic measured at 11 routers)



# Dimension estimation

Local dimension scan statistic for internet traffic

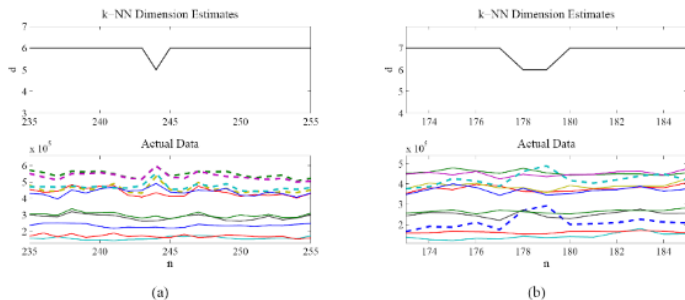


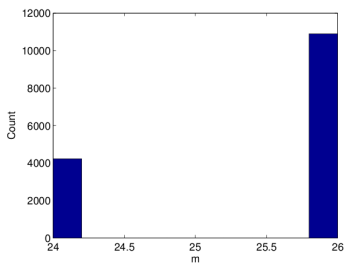
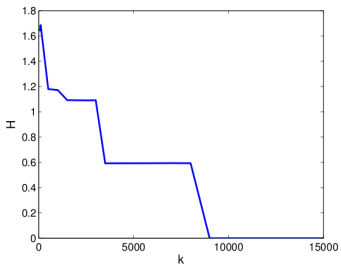
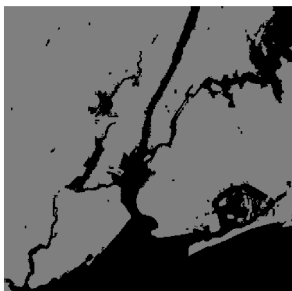
Fig. 3. Zoom shown on two non-obvious complexity changes from data in Fig. 2

**Forensic analysis: Atlanta ( $n=244$ ) and Seattle ( $n=178,179$ ) had high flows (almost 50% of all packets) from/to IP 128.223.216.xxx on port 119.**

Figure: Carter [3]

# Dimension estimation

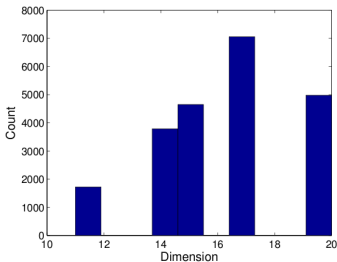
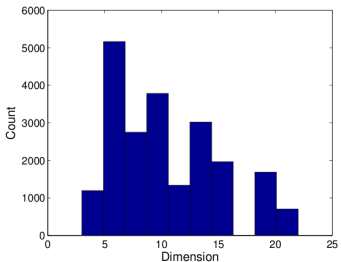
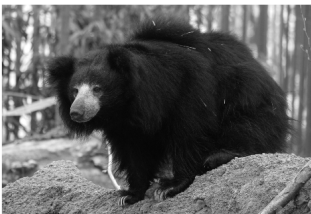
## Dimension-only image segmentation





# Dimension estimation

## Dimension-only image segmentation



# Dimension estimation

## Dimension-only image segmentation



Figure: Carter [2]

# Outline

- 1 Motivation
- 2 Entropy minimization
- 3 Euclidean graphs
- 4 Dimension estimation
- 5 Anomaly detection**
- 6 Conclusions

# BHH theorem extensions

## Outlier Rejection: k-MST

Model:  $f$  is a mixture of nominal and anomalous densities

$$f = (1 - \epsilon)f_o + \epsilon f_1,$$

where

- $f_1$  is an "outlier" density
- $f_o$  is an nominal density
- $\epsilon \in [0, 1]$  is unknown mixture parameter

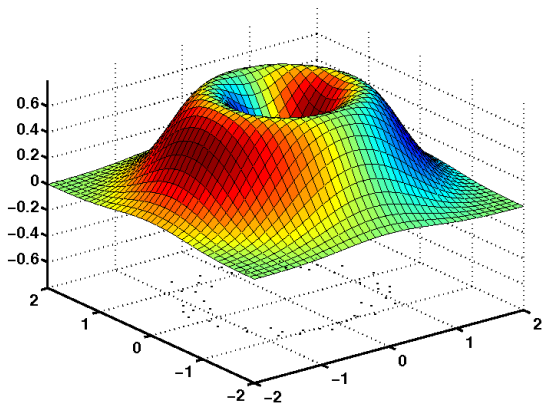
**Objective:** given realization  $\mathcal{X}_n$  from  $f$  cluster the realizations from  $f_o$ .

Two-step k-MST procedure [14]:

- 1 Convert  $f_1$  to maxent (uniform) density via measure transformation
- 2 "Prune" the MST on transformed  $\mathcal{X}_n$  to eliminate vertices arising from maxent density

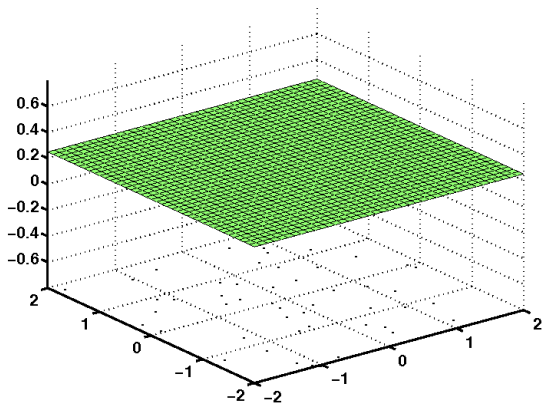
# BHH theorem extensions

Example: Annulus Target Density  $f_1$



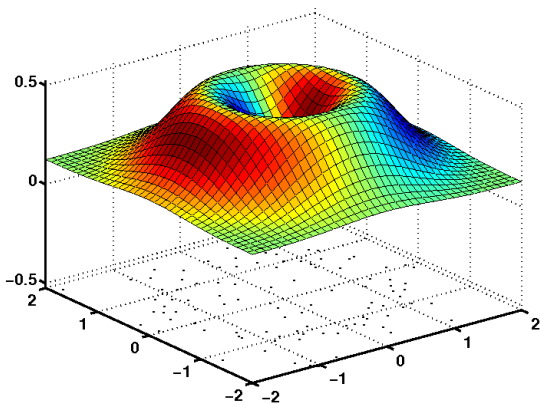
# BHH theorem extensions

Uniform Outlier Density  $f_o$



# BHH theorem extensions

## Mixture Density



# BHH theorem extensions

## $k$ -point Minimal Spanning Tree ( $k$ -MST)

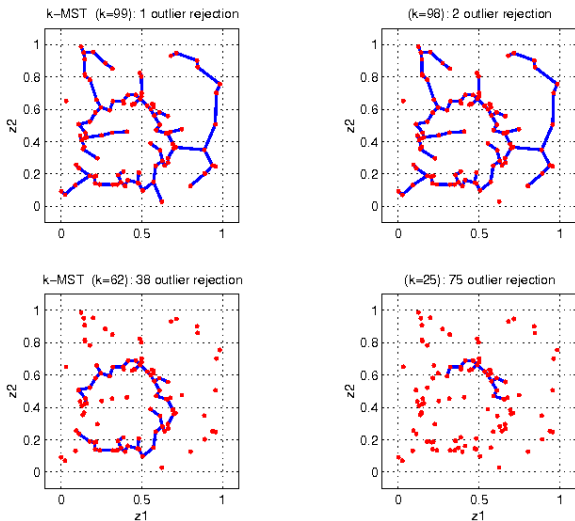
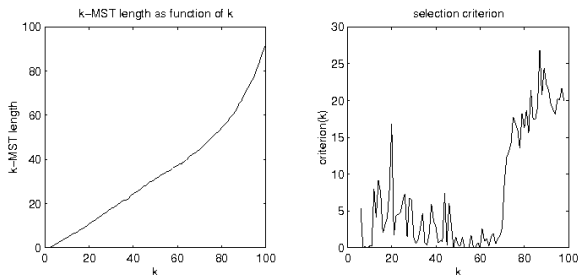


Figure: Clustering an annulus density from uniform noise via  $k$ -MST.



# BHH theorem extensions

## k-MST Stopping Rule



**Figure:** Left:  $k$ -MST curve for 2D annulus density with addition of uniform “outliers” has a knee in the vicinity of  $n - k = 35$ .

# BHH theorem extensions

## Greedy partitioning approximation to k-MST

Ravi and 1996 proposed greedy partitioning approach to k-MST

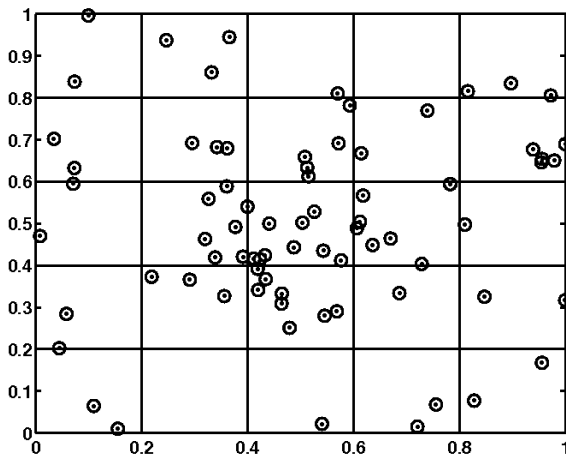


Figure: The case of  $m = 5$  and  $k = 17$ .

# BHH theorem extensions

## Extended BHH Theorem for Greedy k-MST

**Thm:** Fix  $\rho \in [0, 1]$ . If  $k/n \rightarrow \rho$  then the length of the greedy partitioning  $k$ -MST satisfies (Hero and Michel [14])

$$L_\gamma(\mathcal{X}_{n,k}^*)/(\rho n)^\alpha \rightarrow \beta_{L_\gamma, d} \int_S f^\alpha(x|x \in A_o) dx \quad (a.s.)$$

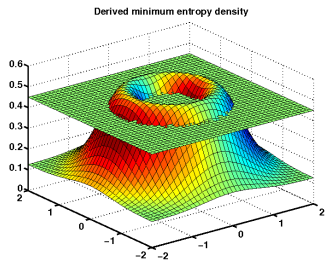
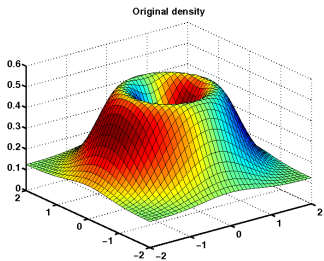
where  $A_o$  is level set of  $f$  which satisfies  $\int_{A_o} f = \rho$ . Alternatively, with

$$H_\alpha(f|x \in A_o) = \frac{1}{1-\alpha} \ln \int_S f^\alpha(x|x \in A_o) dx$$

$$\frac{1}{1-\alpha} \ln (L_\gamma(\mathcal{X}_{n,k}^*)/(\rho n)^\alpha) \rightarrow \beta_{L_\gamma, d} H_\alpha(f|x \in A_o) + c \quad (a.s.)$$

# BHH theorem extensions

Waterpouring solution = Level set of density



Note:  $P(X \in A_0) = \rho$

# Anomaly detection

## Optimality of level set

Consider optimal test of hypotheses on  $f(x) = (1 - \epsilon)f_0(x) + \epsilon U(x)$

$$H_0 : \epsilon = 0 \quad (1)$$

$$H_1 : \epsilon > 0 \quad (2)$$

based on a sample  $\mathbf{X} = [X_1, \dots, X_n]$ ,  $X_i \in [0, 1]^d$  and  $\epsilon \in [0, 1]$ .

When  $f_0$  and  $U(x)$  are known, most powerful test of level

$\alpha = 1 - \rho$  is LRT

$$\Lambda(\mathbf{X}) = \frac{f(\mathbf{X}|H_1)}{f(\mathbf{X}|H_0)} \underset{H_0}{\overset{H_1}{>}} \eta$$

where  $\eta$  is a threshold chosen to satisfy  $P(\Lambda(\mathbf{X}) > \eta | H_0) = 1 - \rho$

# Anomaly detection

## Level set estimation

If  $U(x)$  is uniform density then

$$\Lambda(\mathbf{X}) > 0 \text{ iff } f_0(\mathbf{X}) > \gamma = \frac{\eta - \epsilon}{1 - \epsilon}$$

which is equivalent to

### Definitions (Level set test)

Decide  $H_1$  if  $\mathbf{X} \notin A_0$

where  $A_0$  is the level set satisfying  $\int_{A_0} f_0(x) dx = 1 - \rho$ .

**Note:** The decision region of the most powerful test does not depend on  $\epsilon$

$\Rightarrow$  test is **uniformly most powerful** over  $\epsilon$

For unknown  $f_0$  the level set test can be implemented using K-MST

# Anomaly detection

## Leave-one-out kNNG approximation to k-MST

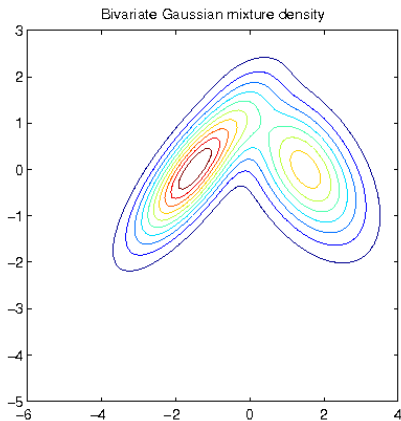


Figure: Bivariate mixture of Gaussians density

# Anomaly detection

## Greedy K-MST test example

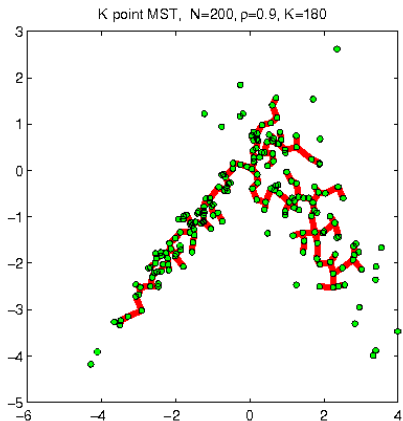
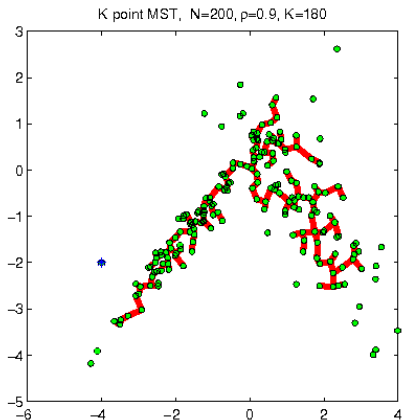


Figure: K-MST over a training realization from MoG



# Anomaly detection

## Greedy K-MST test example



**Figure:** K-MST fails to capture new point (blue asterisk is outlier)

# Anomaly detection

## Greedy K-MST test example

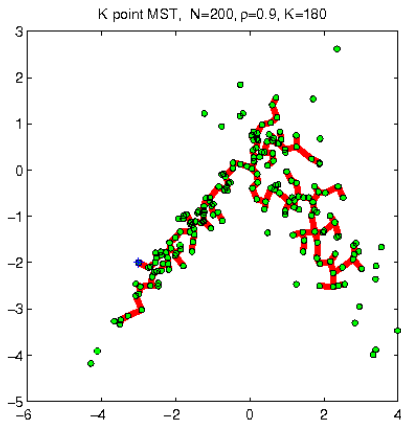


Figure: K-MST capture new point (blue asterisk is inlier)

# Anomaly detection

## Greedy K-MST test example

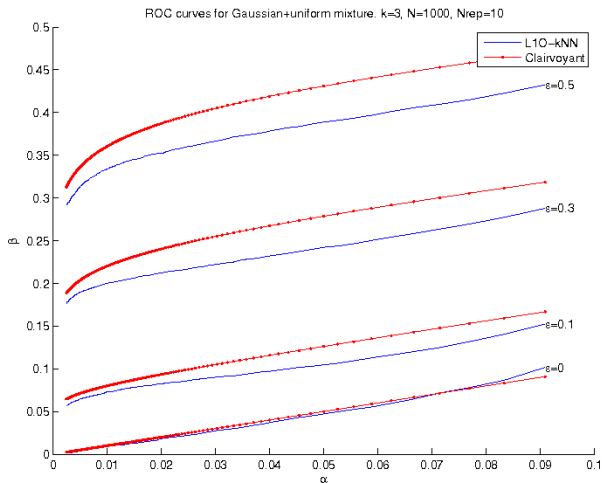


Figure: ROC curves for L10-kNNG approximation are close to UMP curves for Gaussian example

# Activity detection

## Sensor network activity detection experiment

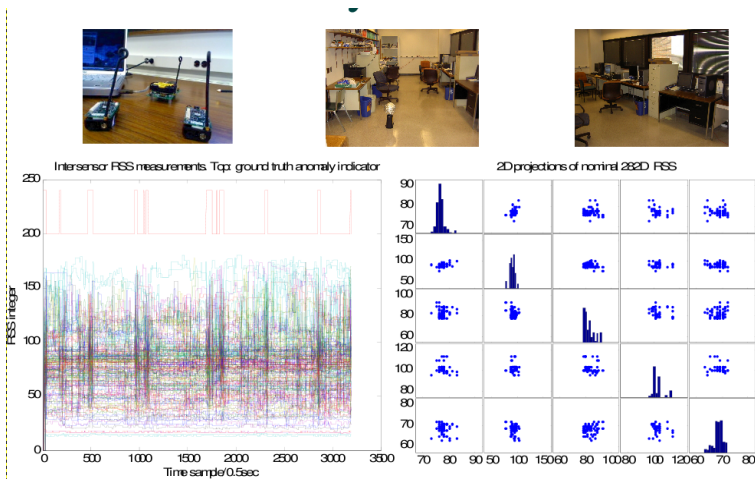
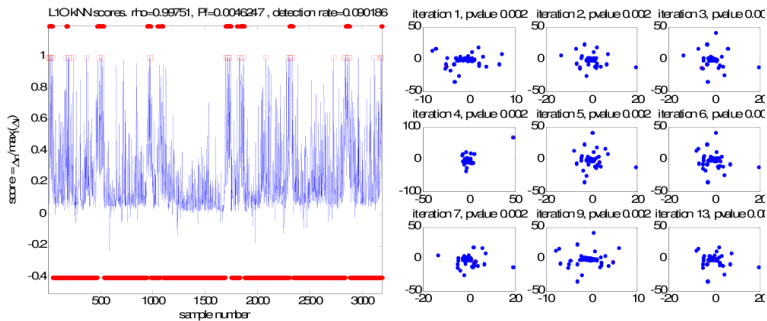


Figure: Hero [11]

# Anomaly detection

## Sensor network activity detection experiment



**Figure:** Online activity detector statistic (Left) some anomalies detected (right)

# Outline

- 1 Motivation
- 2 Entropy minimization
- 3 Euclidean graphs
- 4 Dimension estimation
- 5 Anomaly detection
- 6 Conclusions**






# Conclusions






- Minimum entropy principle is fundamental in statistical estimation and learning
- Geometric graphs are alternatives to density plug-in estimates of entropy, topological dimension, and level sets from random samples.
- Bounds on convergence rates are available (AH and Costa [12], Costa and AH [5], AH and Michel [14]).
- Results generalize to non-Euclidean geometries such as information geometries of distributions (Carter [2]).

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