

Group meeting – November 6, 2013

Stable Multi-Scale Signatures for Shapes using Topological Persistence

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Stable Multi-Scale Signatures for Shapes using Topological Persistence

→ joint projects with Fred, Vin, Leo, David, etc.

Nomenclature

In our work and throughout the talk:

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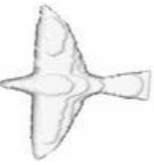



- *shape* \equiv compact metric space (sometimes assumed finite or manifold)
- *distance between shapes* \equiv Gromov-Hausdorff (GH) distance
- *signature* \equiv persistence diagram (choose the filtration)
 - *multi-scale* \equiv reflects the structure of the shape across scales
 - *global/local* \equiv attached to the whole shape / to a (set of) base point(s)
 - *stable* \equiv variations with GH-distance and base point location are controlled

Why Compare Shapes

Comparisons between shapes occur in various contexts, including:

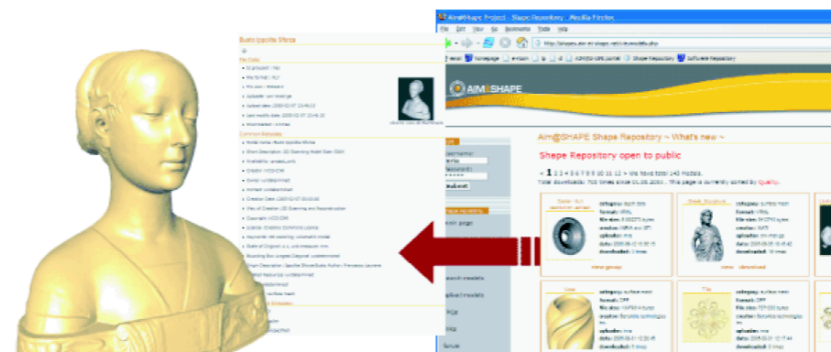
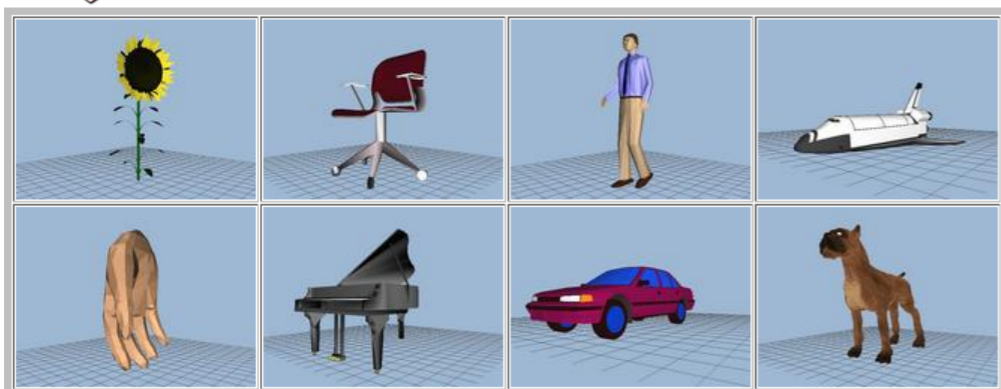
- shape classification (organizing large databases of shapes)



| | | | | |
|---|---|---|---|---|
|  |  |  |  |  |
| Tables | Cups | Chairs | Airplanes | Dolphins |
|  |  |  |  | |
| Birds | Four-limbs | Dinosaurs | Fishes | |

Princeton Shape Retrieval and Analysis Group
Princeton Shape Benchmark

McGill Shape Benchmark

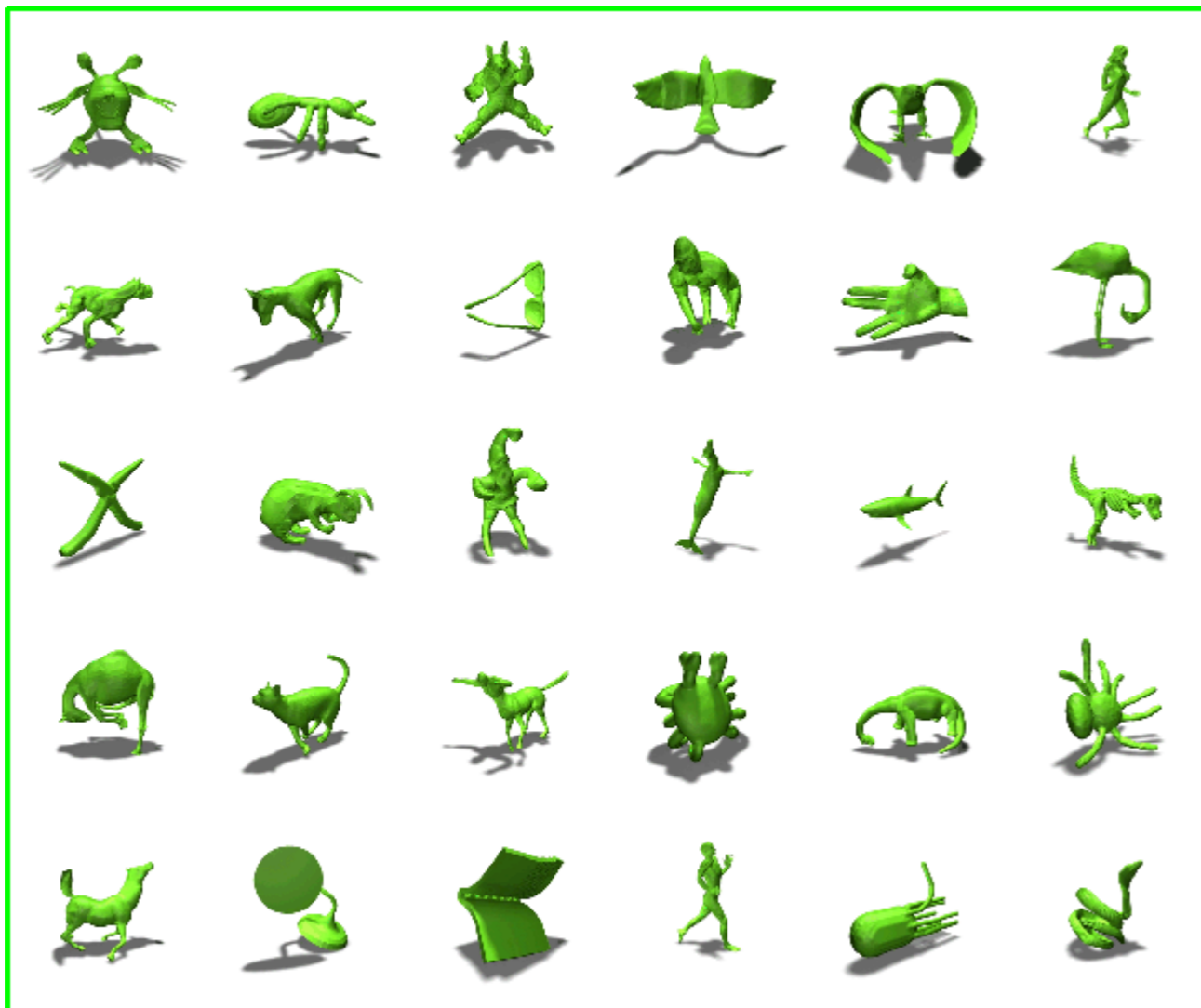


AIM SHAPE
Digital Shape WorkBench

Why Compare Shapes

Comparisons between shapes occur in various contexts, including:

- shape classification (organizing large databases of shapes)
- shape retrieval (searching in databases of shapes)

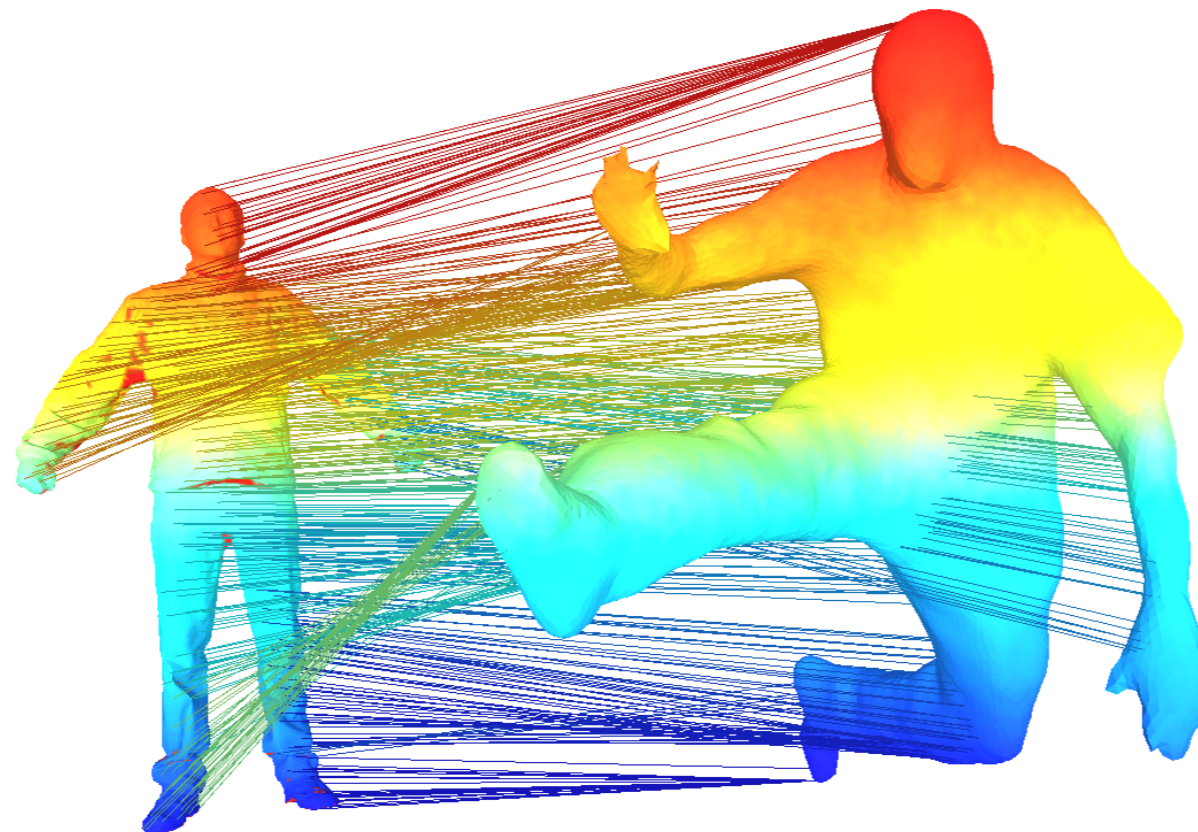


source: SHREC (Shape Retrieval Contest) 2011

Why Compare Shapes

Comparisons between shapes occur in various contexts, including:

- shape classification (organizing large databases of shapes)
- shape retrieval (searching in databases of shapes)
- partial/global shape matching (finding the *best* mapping between shapes)



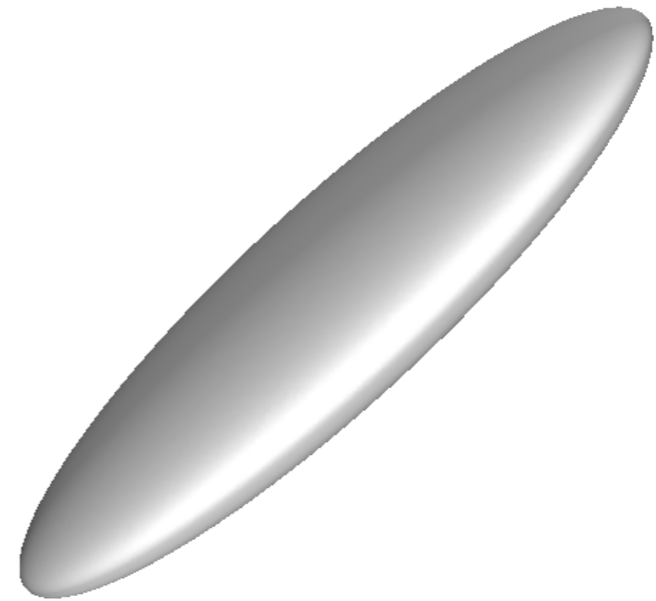
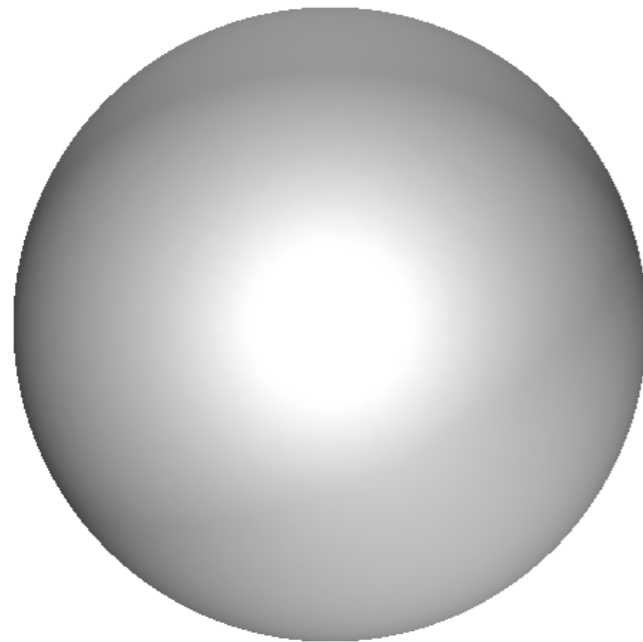
Why Compare Shapes

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- partial/global shape matching (finding the *best* mapping between shapes)

shape comparison is but one piece of the whole process, yet it is a crucial piece

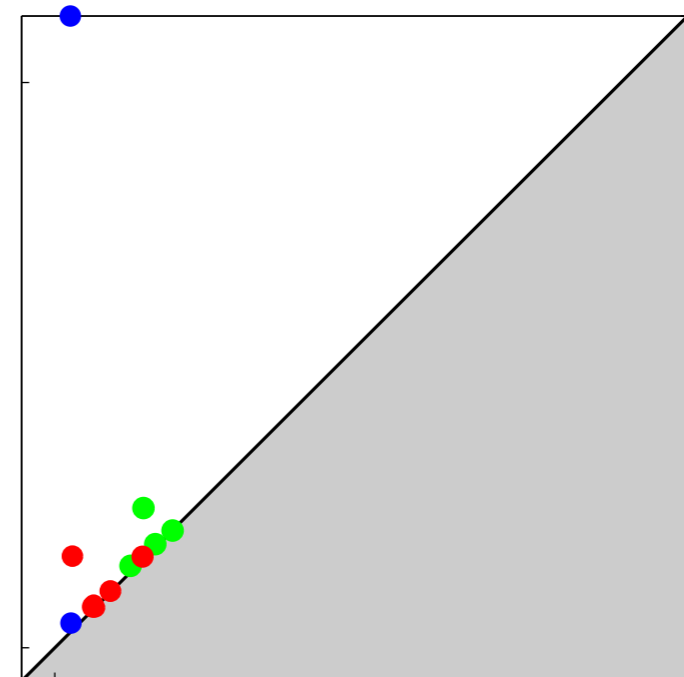
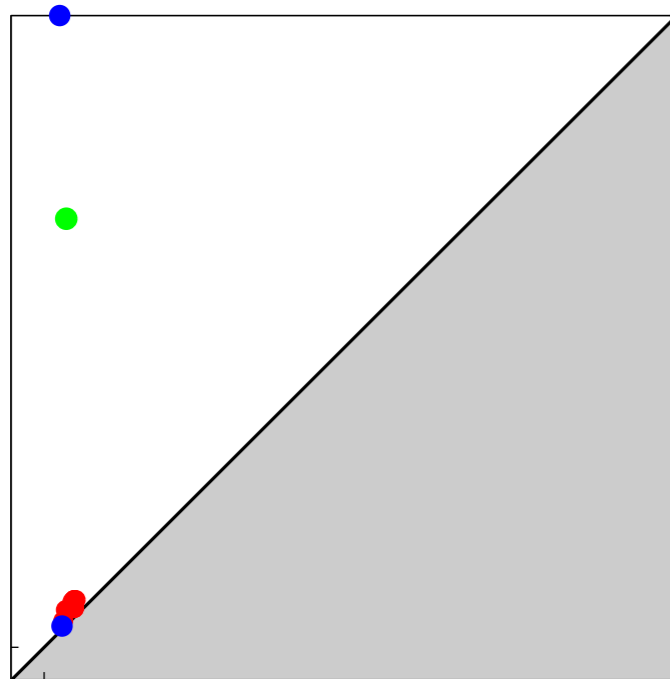
Why use Signatures



isometries
GH distance
hard to compute

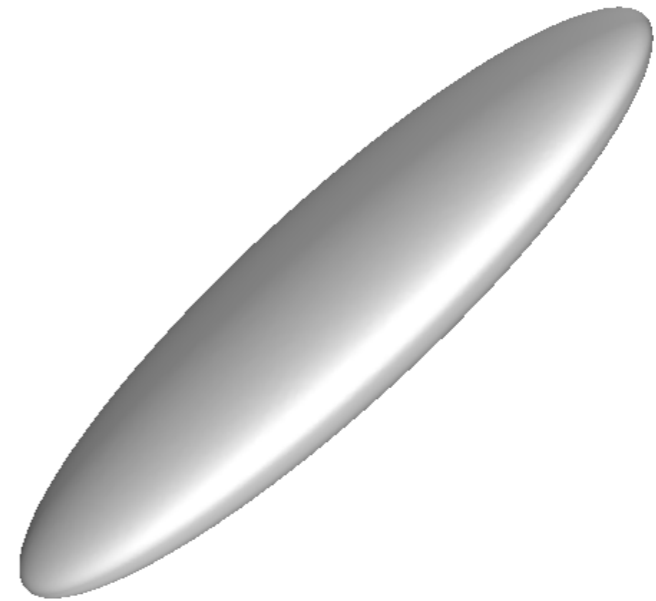
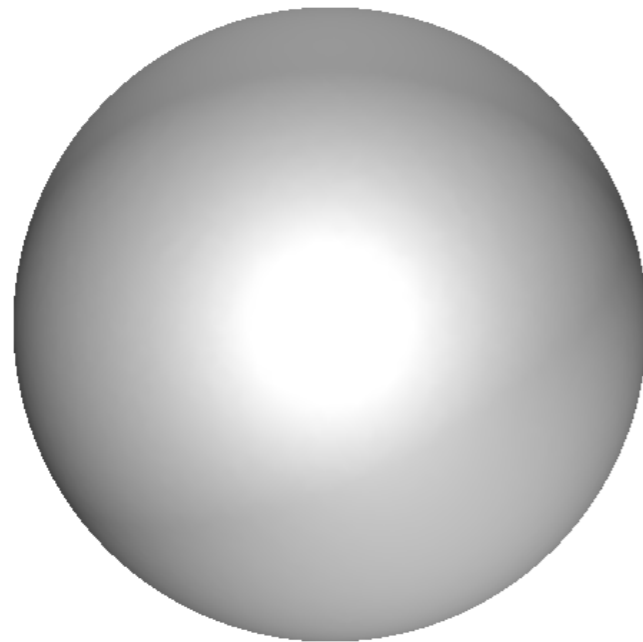
shapes space

signatures space



equality
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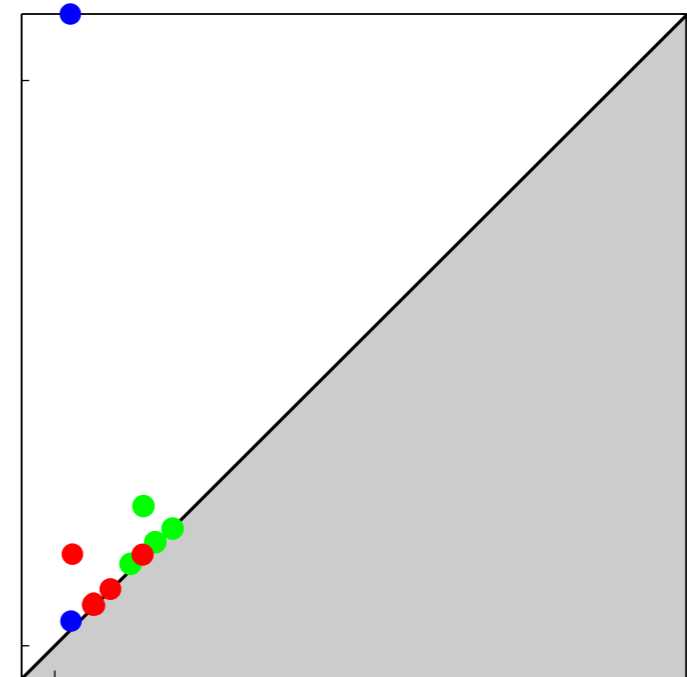
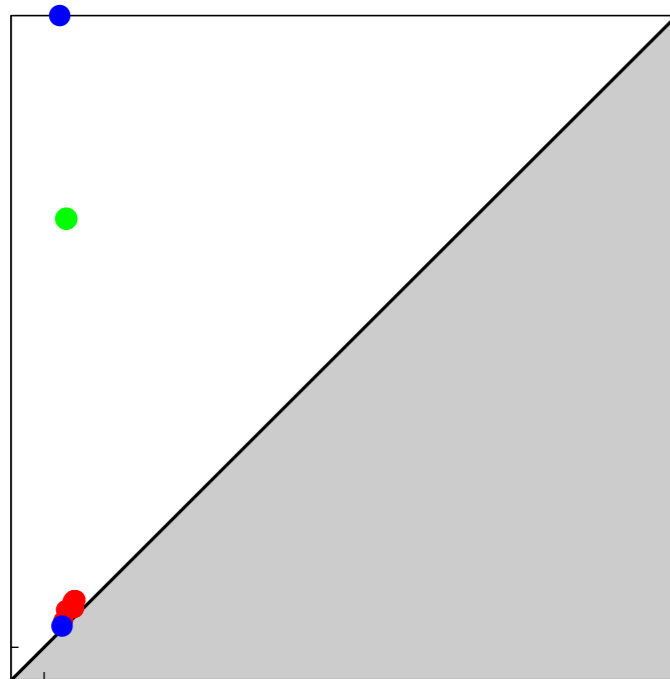


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shapes space

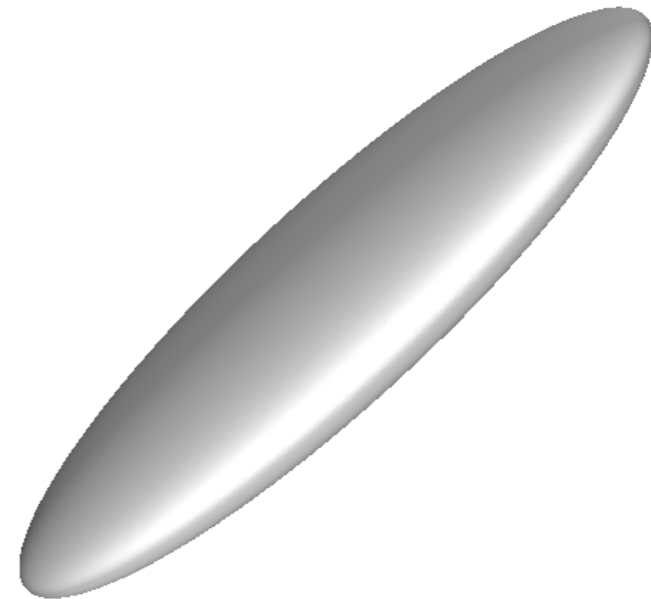
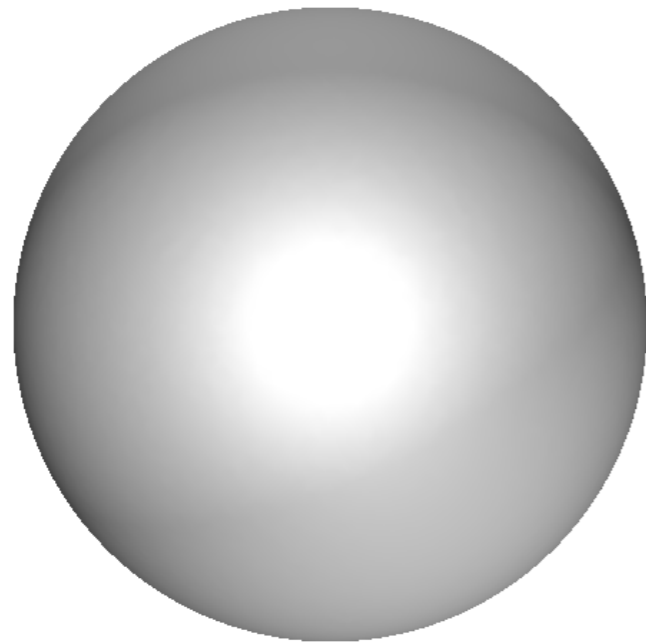
Ideally, signatures distance = GH distance

signatures space



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Why use Signatures



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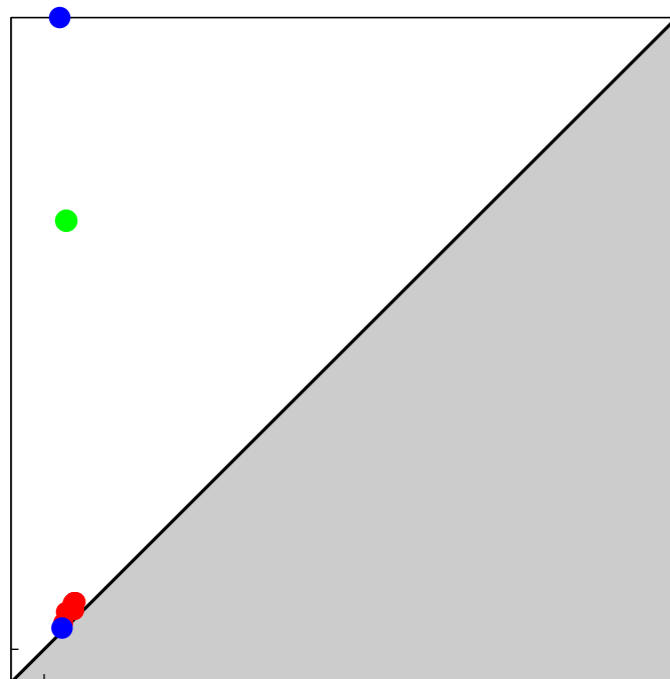
shapes space

signatures space

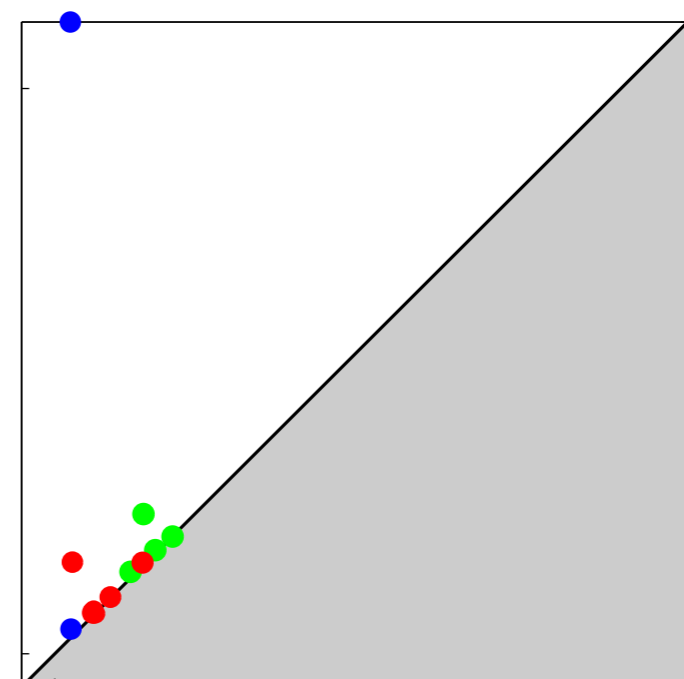
Ideally, signatures distance = GH distance

In reality,

\leq



equality
distance
easy to compute



Rips-Based Signatures

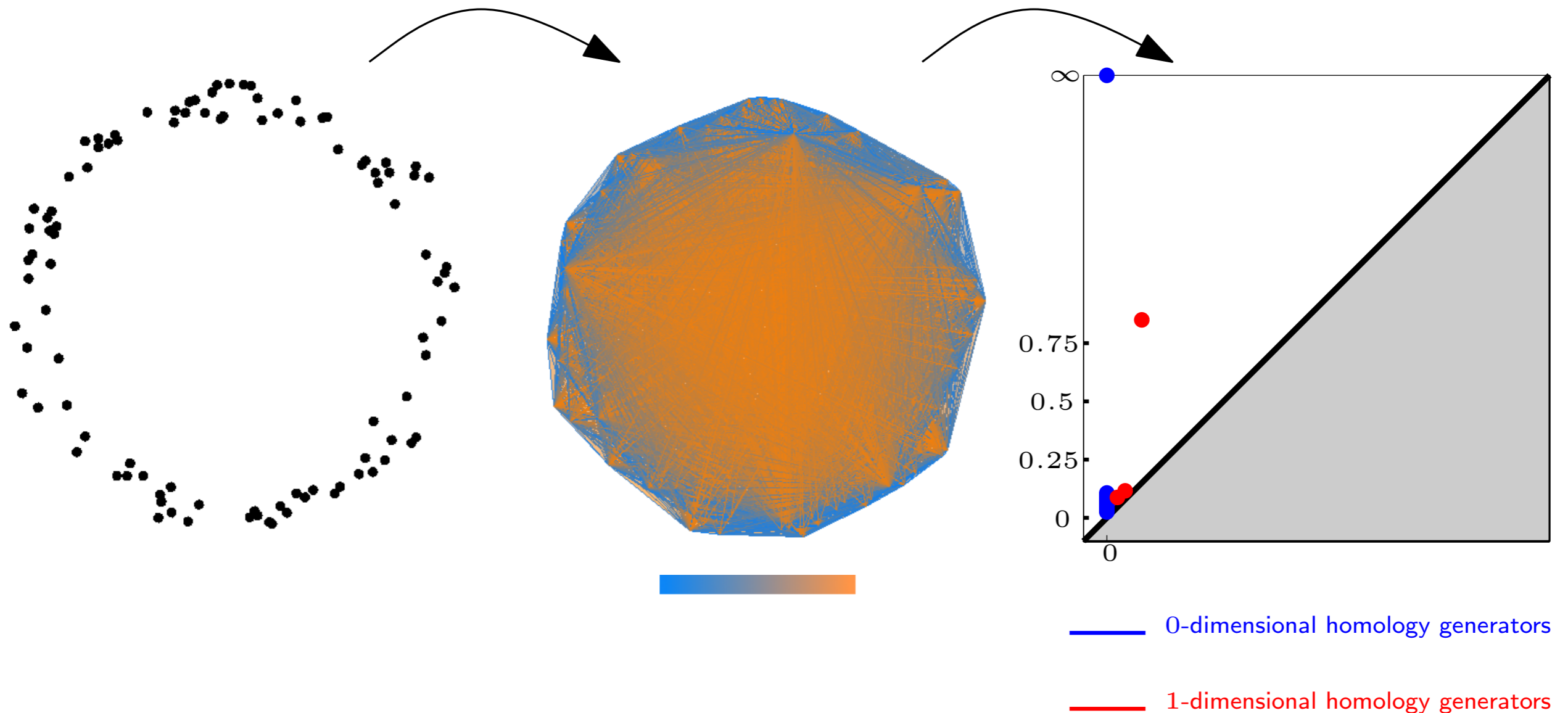
Input: a compact metric space (X, d_X)

Signature: $\text{Dg } \mathcal{R}(X, d_X)$, where $\mathcal{R}(X, d_X)$ is the *Rips filtration* of (X, d_X)

Rips-Based Signatures

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Rips-Based Signatures (continued)

Theorem (Stability): For any compact metric spaces (X, d_X) and (Y, d_Y) , $d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) \leq 2d_{\text{GH}}(X, Y)$ (plus diags are well-defined).

Variants [Chazal, de Silva, Oudot '12/'13/'14?]:

- Čech complexe/ *extrinsic* Čech complex filtrations
- Witness complex filtrations (landmarks fixed)
- precompact metric spaces
- (dis-)similarity measures

Rips-Based Signatures (continued)

finite

Theorem (Stability): For any ~~compact~~ metric spaces (X, d_X) and (Y, d_Y) , $d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) \leq 2d_{\text{GH}}(X, Y)$ (plus diags are well-defined).

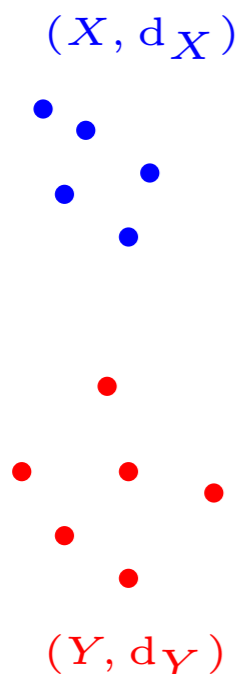
Proof:

Rips-Based Signatures (continued)

finite

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Proof: Take any $\varepsilon > d_{\text{GH}}(X, Y)$.



$$d_{\text{GH}}(X, Y) < \varepsilon$$

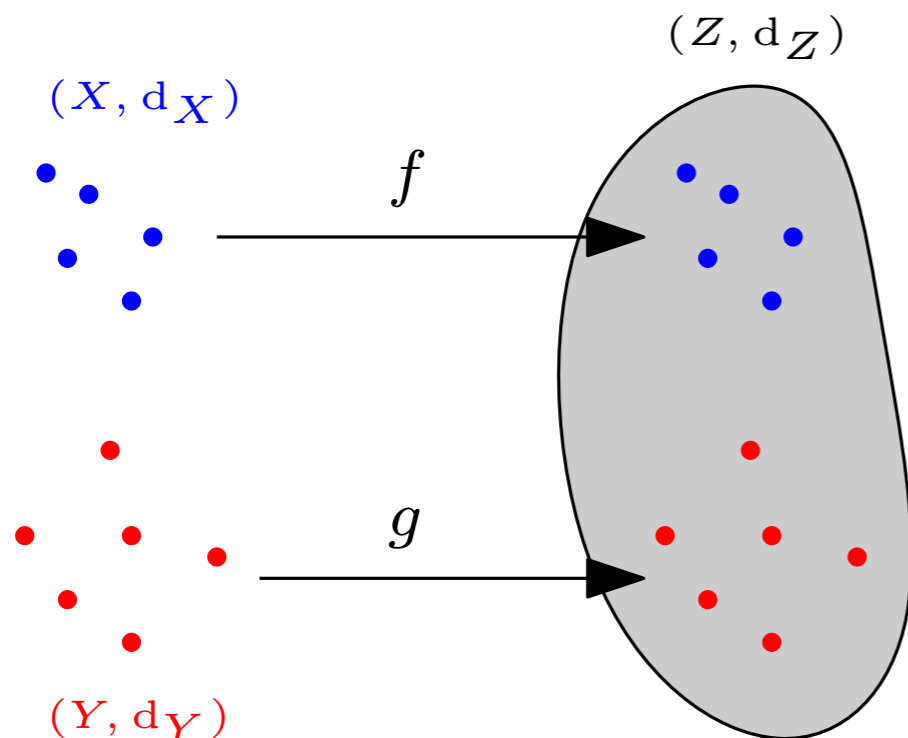
$$d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y))$$

Rips-Based Signatures (continued)

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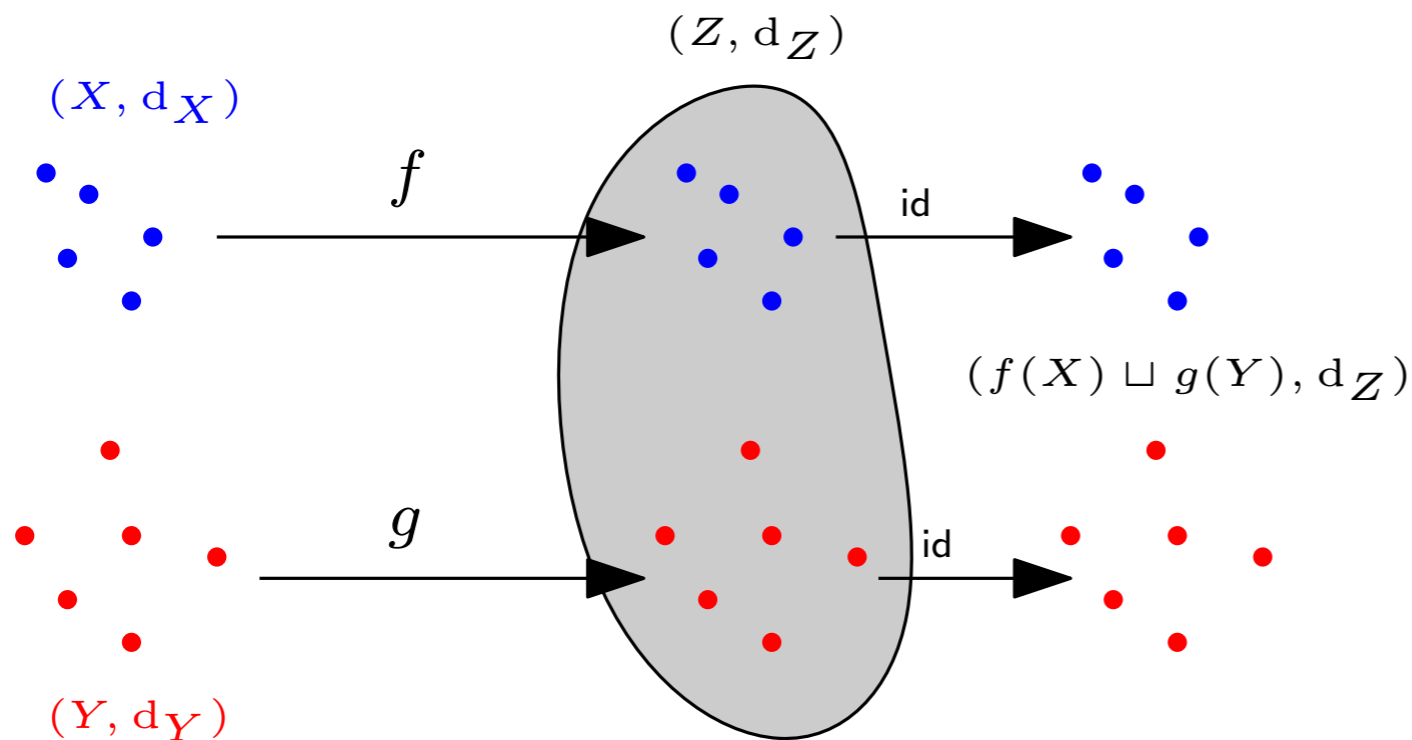
$$d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) = d_B^\infty(\text{Dg } \mathcal{R}(f(X), d_Z), \text{Dg } \mathcal{R}(g(Y), d_Z))$$

Rips-Based Signatures (continued)

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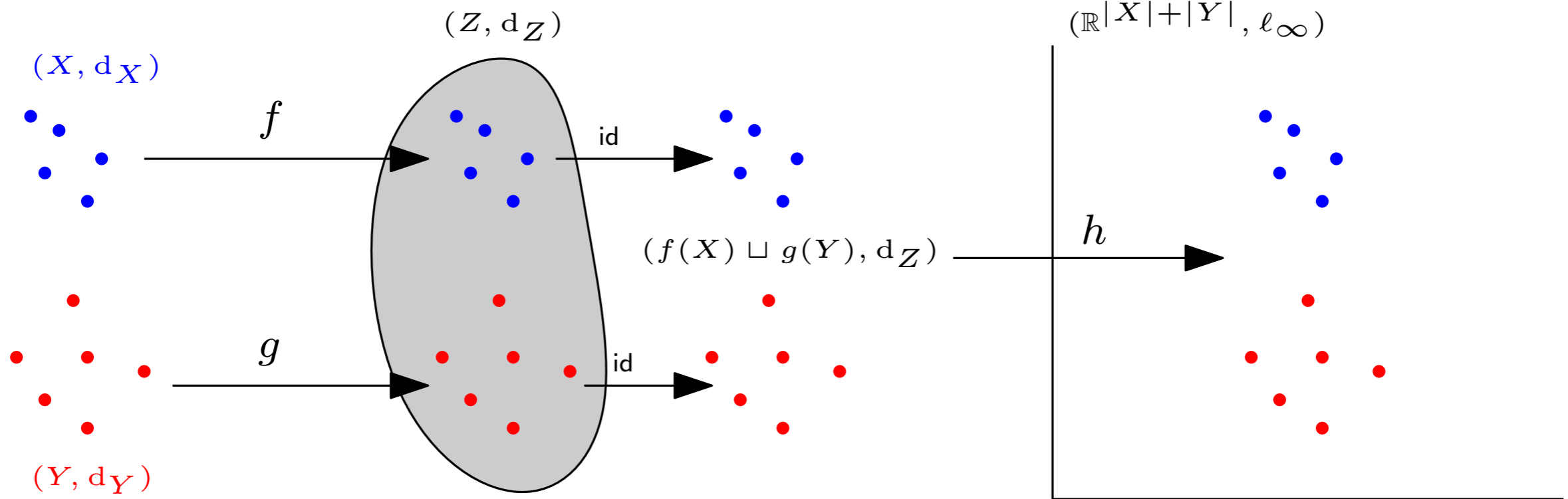
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$$d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) = d_B^\infty(\text{Dg } \mathcal{R}(f(X), d_Z), \text{Dg } \mathcal{R}(g(Y), d_Z))$$

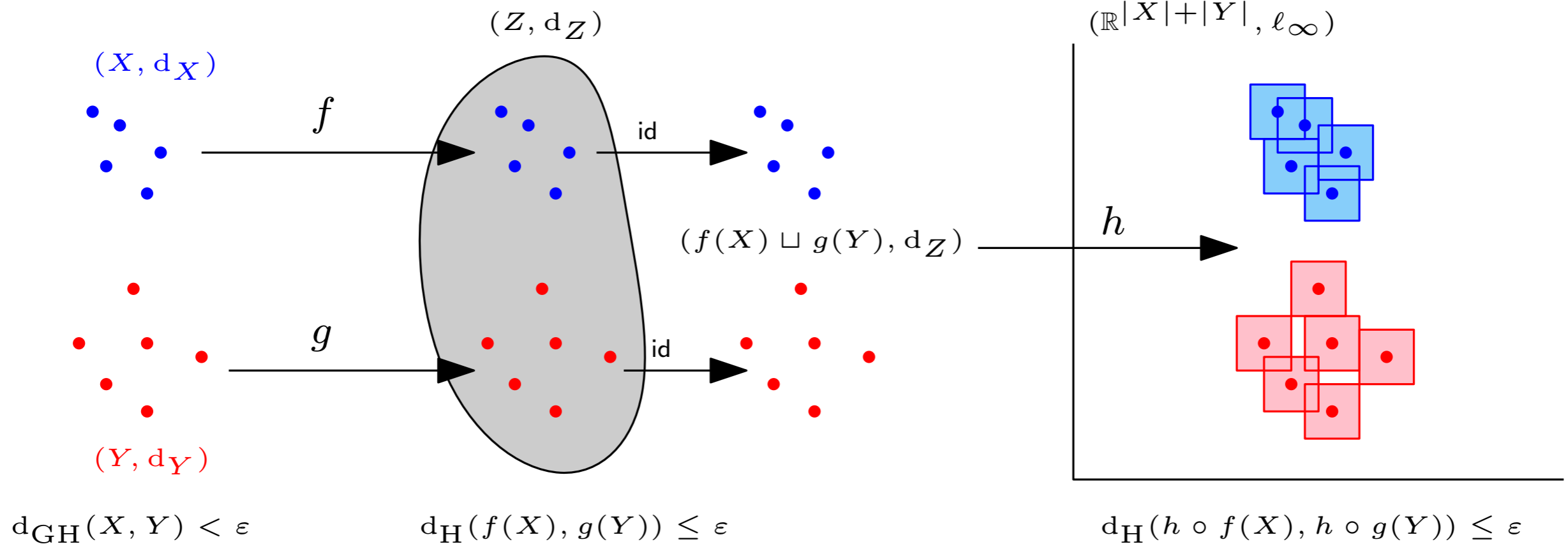
$$= d_B^\infty(\text{Dg } \mathcal{R}(h \circ f(X), \ell_\infty), \text{Dg } \mathcal{R}(h \circ g(Y), \ell_\infty))$$

Rips-Based Signatures (continued)

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$$= d_B^\infty(\text{Dg } \mathcal{R}(h \circ f(X), \ell_\infty), \text{Dg } \mathcal{R}(h \circ g(Y), \ell_\infty))$$

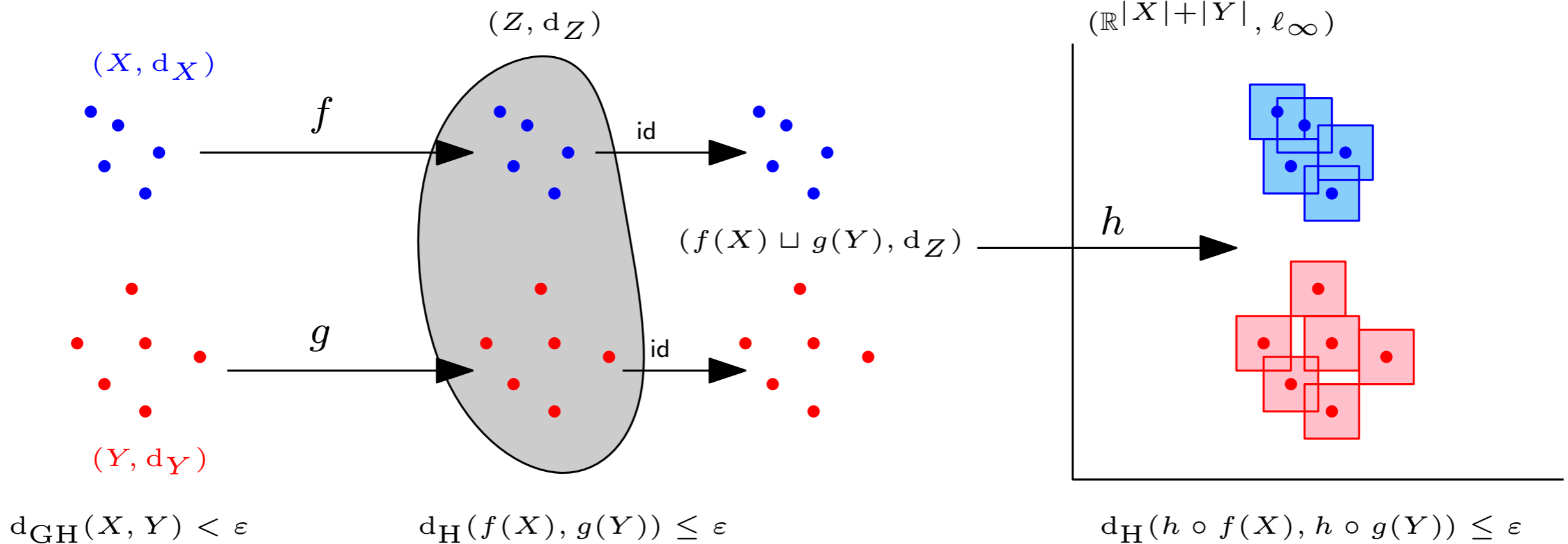
$$= 2 d_B^\infty(\text{Dg } \mathcal{C}(h \circ f(X), \text{Dg } \mathcal{C}(h \circ g(Y)))$$

Rips-Based Signatures (continued)

finite

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Proof: Take any $\varepsilon > d_{\text{GH}}(X, Y)$.



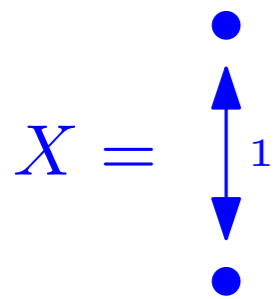
$$\begin{aligned}
 d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) &= d_B^\infty(\text{Dg } \mathcal{R}(f(X), d_Z), \text{Dg } \mathcal{R}(g(Y), d_Z)) \\
 &= d_B^\infty(\text{Dg } \mathcal{R}(h \circ f(X), \ell_\infty), \text{Dg } \mathcal{R}(h \circ g(Y), \ell_\infty)) \\
 &= 2 d_B^\infty(\text{Dg } \mathcal{C}(h \circ f(X), \text{Dg } \mathcal{C}(h \circ g(Y))) \\
 &= 2 d_B^\infty(\text{Dg } d_\infty(\cdot, h \circ f(X)), \text{Dg } d_\infty(\cdot, h \circ g(Y))) \leq 2\varepsilon. \quad \square
 \end{aligned}$$

Rips-Based Signatures (continued)

finite

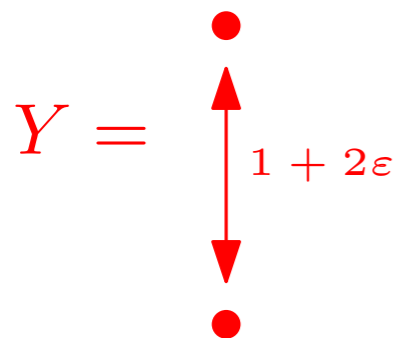
Theorem (Stability): For any ~~compact~~ metric spaces (X, d_X) and (Y, d_Y) , $d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) \leq 2d_{\text{GH}}(X, Y)$ (plus diags are well-defined).

The bound is worst-case tight...



$$d_{\text{GH}}(X, Y) = \varepsilon$$

$$\text{Dg } \mathcal{R}(X, d_X) = \{(0, \infty), (0, 1)\}$$



$$\text{Dg } \mathcal{R}(Y, d_Y) = \{(0, \infty), (0, 1 + 2\varepsilon)\}$$

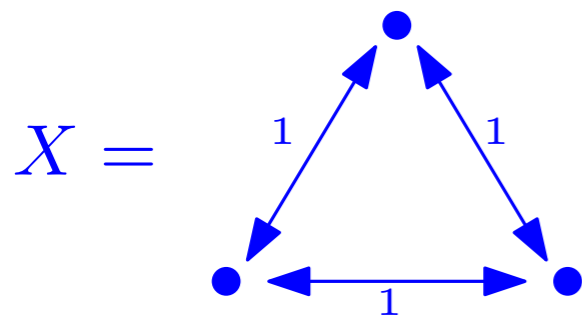
$$\Rightarrow d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) = 2\varepsilon$$

Rips-Based Signatures (continued)

finite

Theorem (Stability): For any ~~compact~~ metric spaces (X, d_X) and (Y, d_Y) , $d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) \leq 2d_{\text{GH}}(X, Y)$ (plus diags are well-defined).

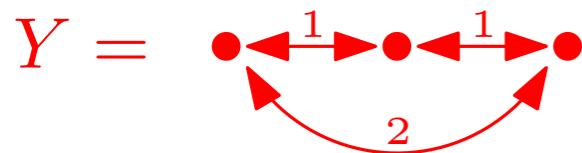
The bound is worst-case tight... but it is still only an upper bound



$$d_{\text{GH}}(X, Y) = \frac{1}{2}$$

$$\text{Dg } \mathcal{R}(X, d_X) = \{(0, \infty), (0, 1), (0, 1)\}$$

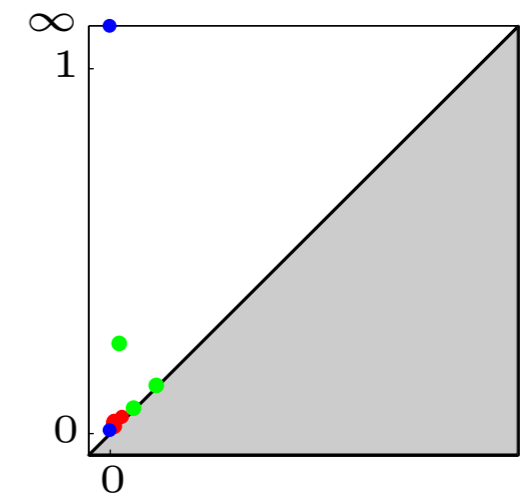
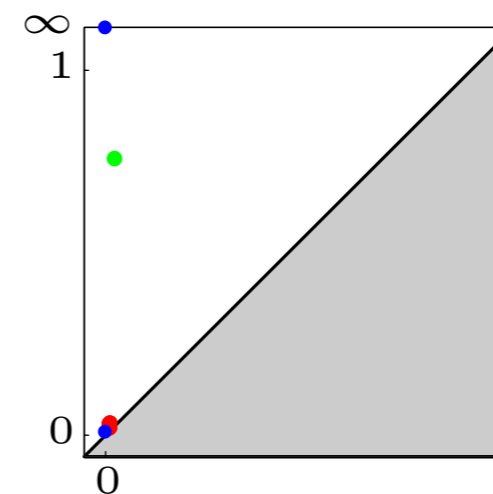
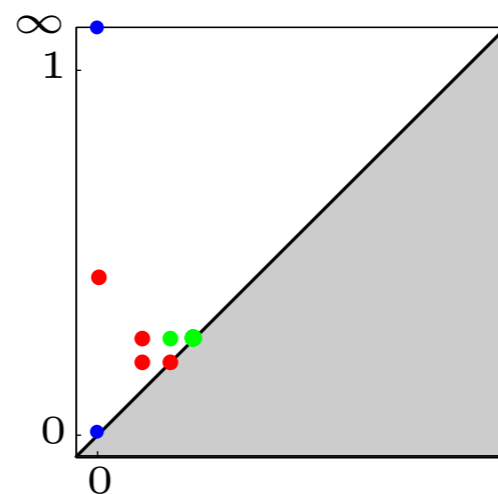
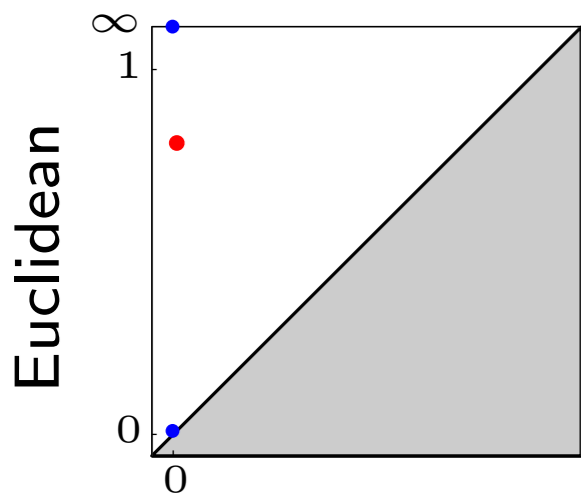
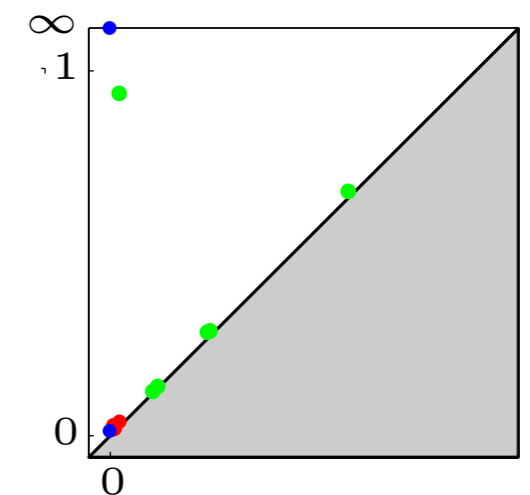
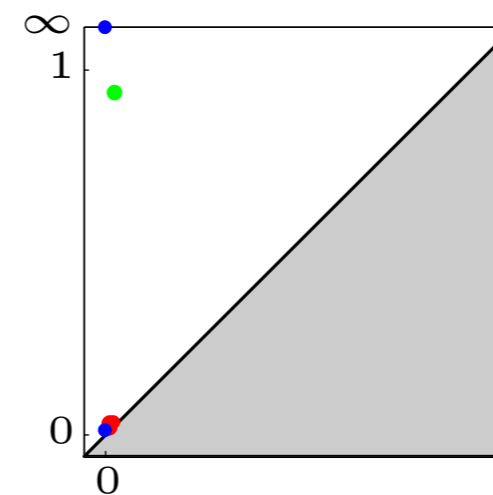
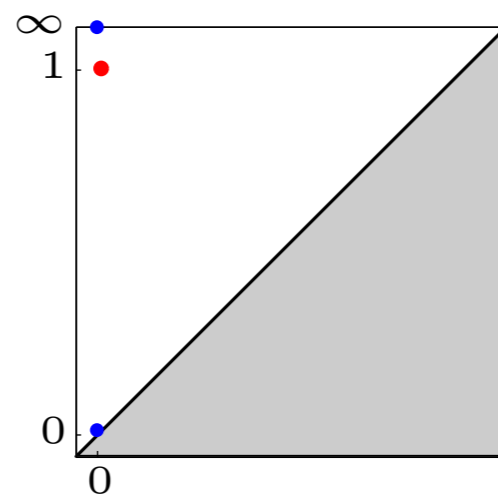
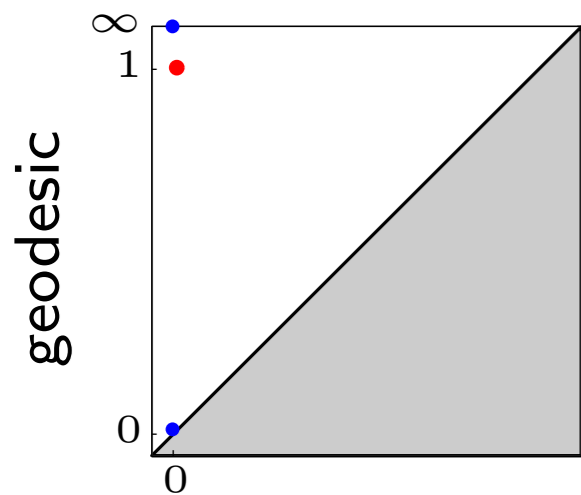
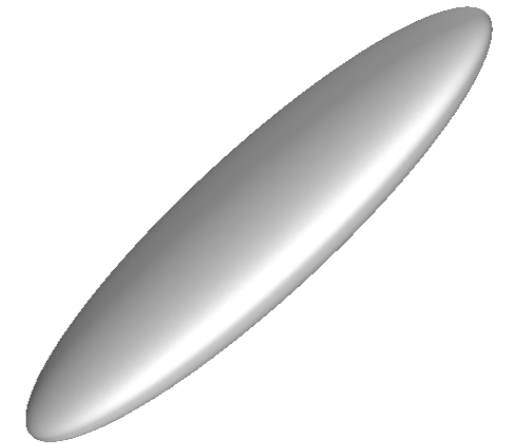
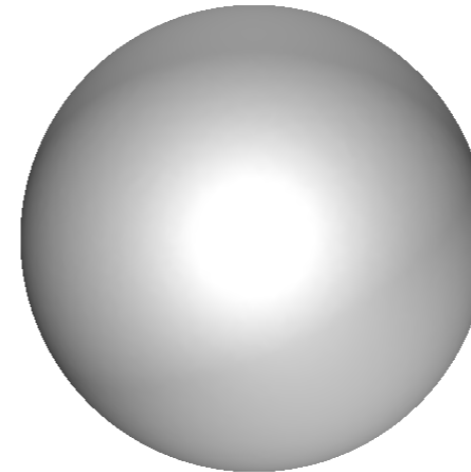
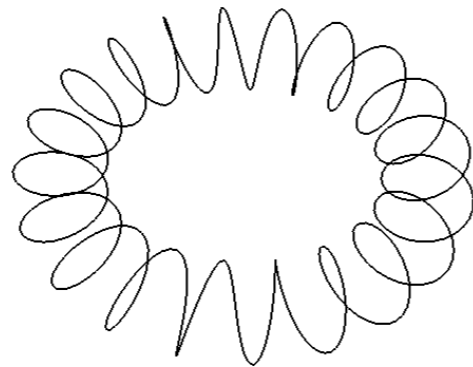
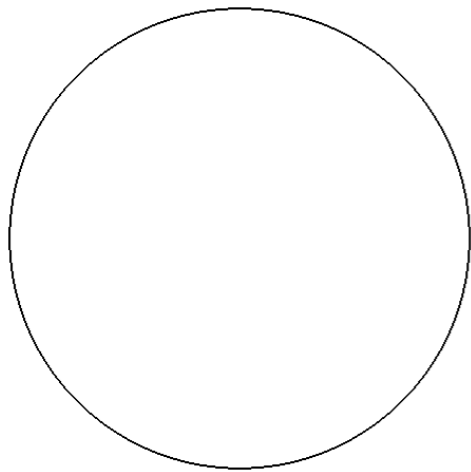
$$\text{Dg } \mathcal{R}(Y, d_Y) = \{(0, \infty), (0, 1), (0, 1)\}$$



$$\Rightarrow d_B^\infty(\text{Dg } \mathcal{R}(X, d_X), \text{Dg } \mathcal{R}(Y, d_Y)) = 0$$

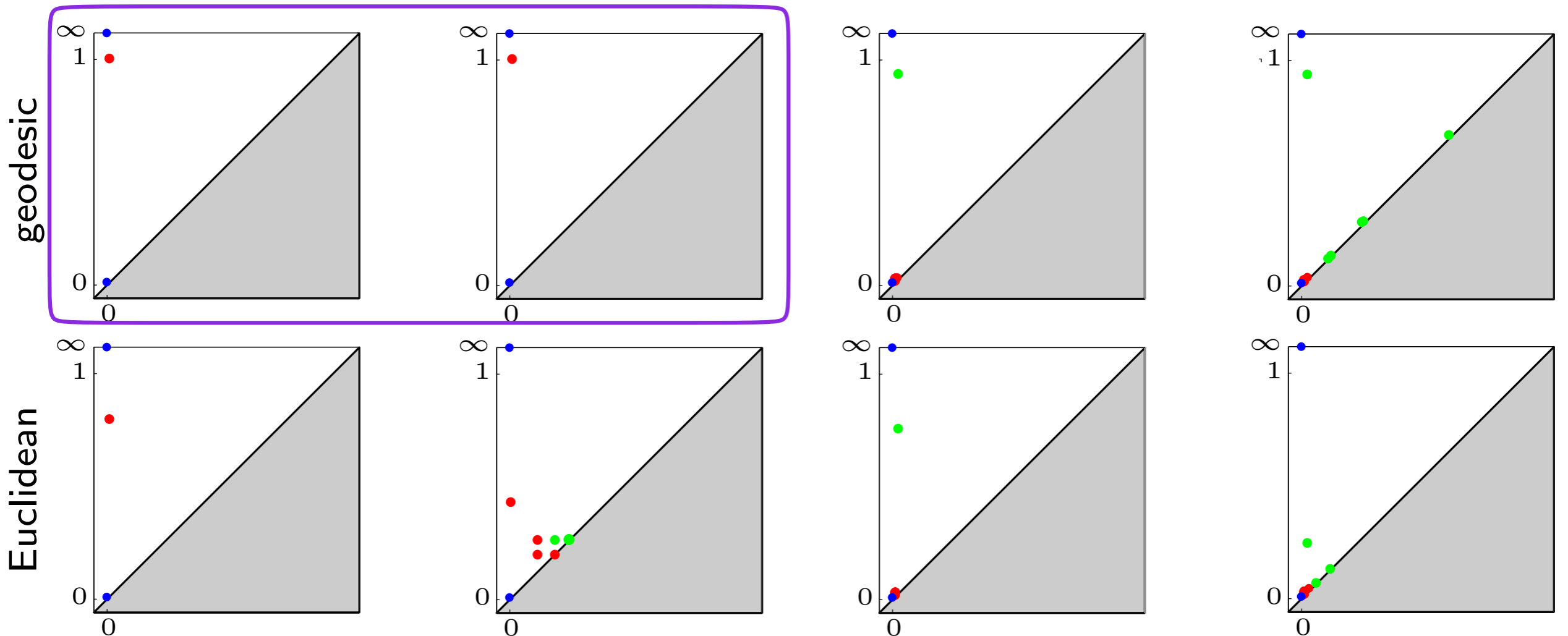
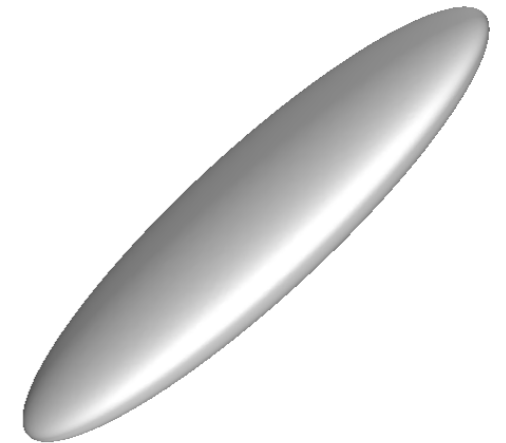
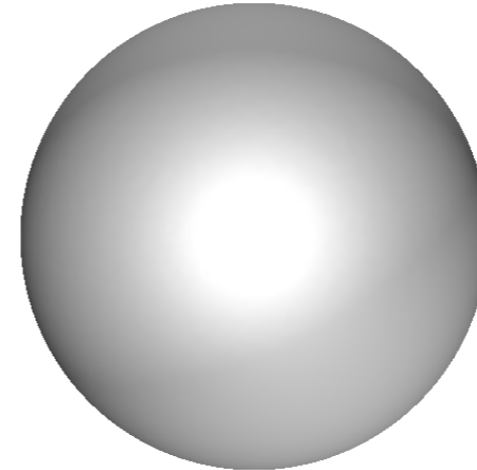
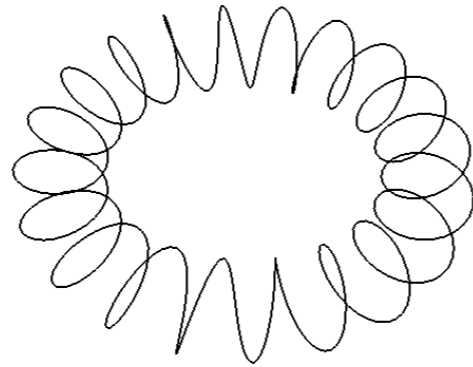
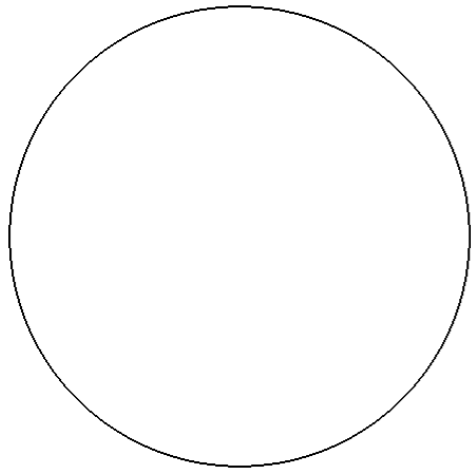
Rips-Based Signatures (continued)

Signatures of some elementary shapes (approximated from finite samples):



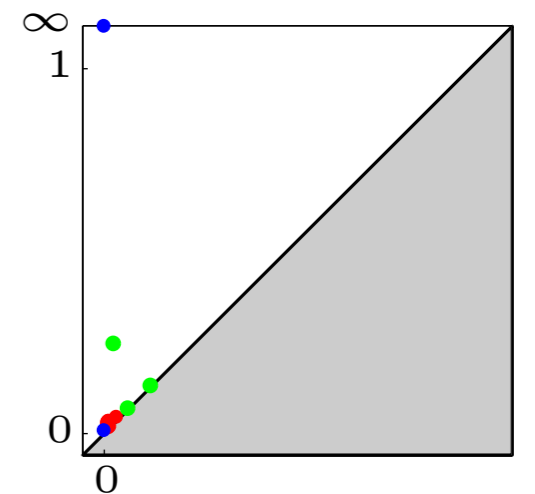
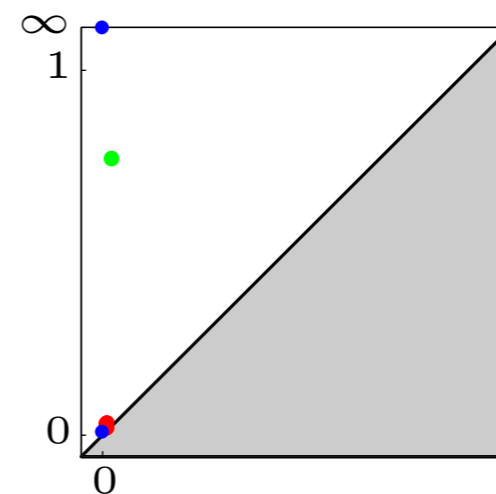
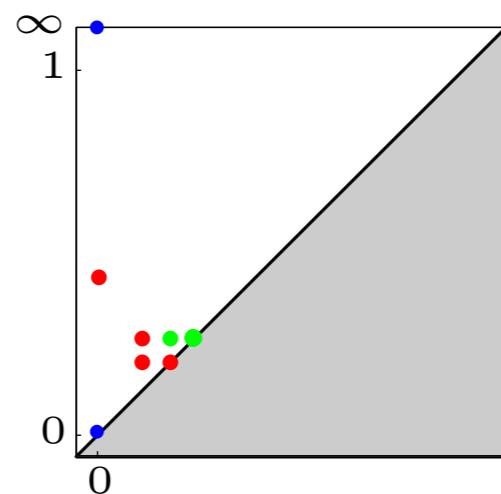
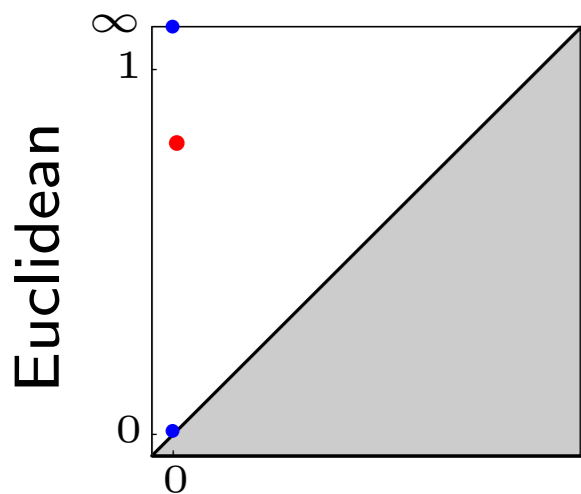
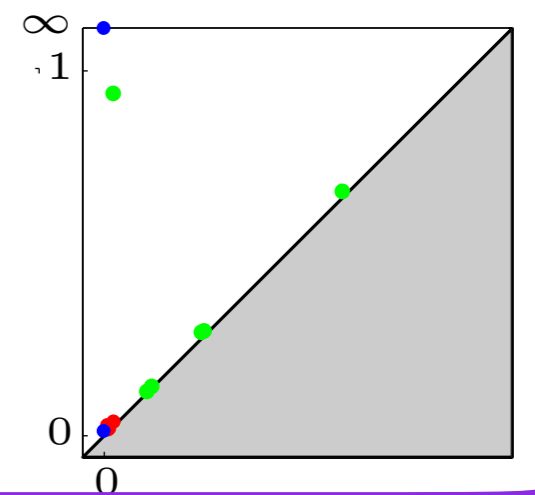
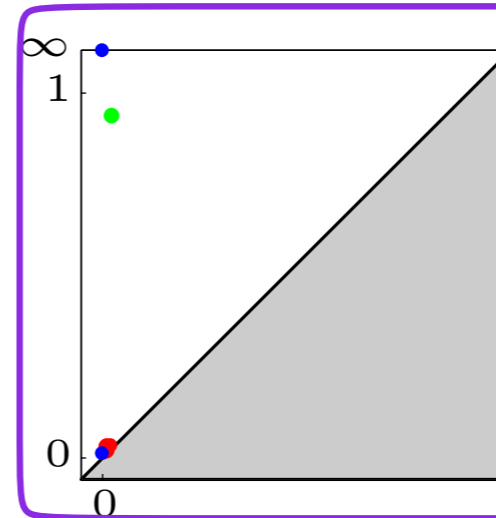
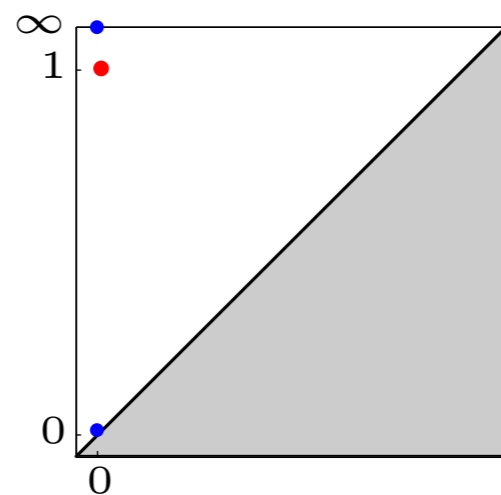
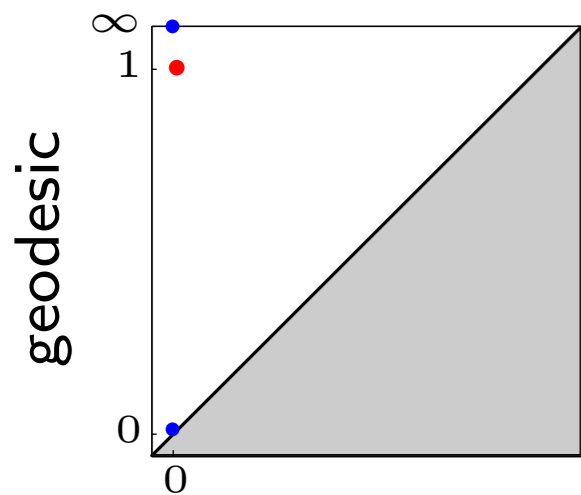
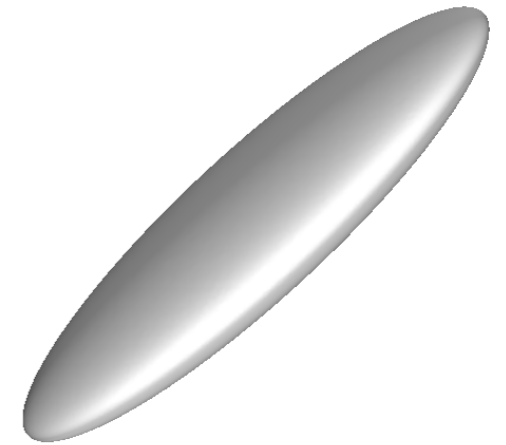
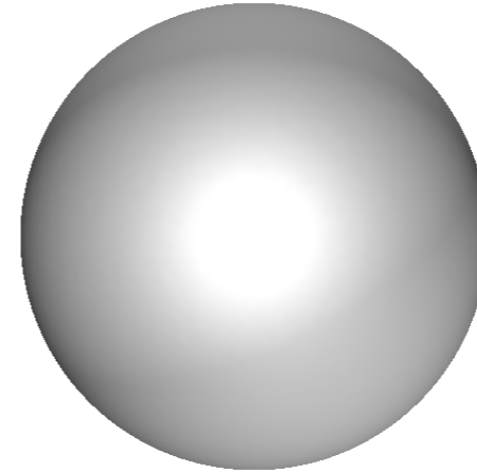
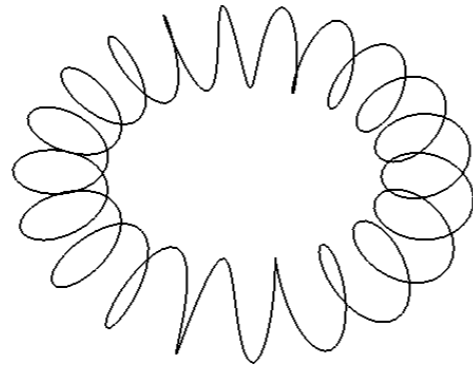
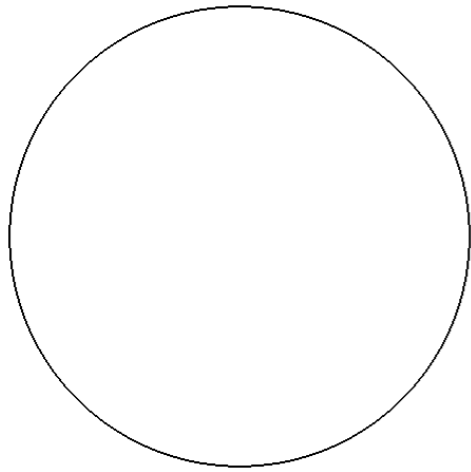
Rips-Based Signatures (continued)

Signatures of some elementary shapes (approximated from finite samples):



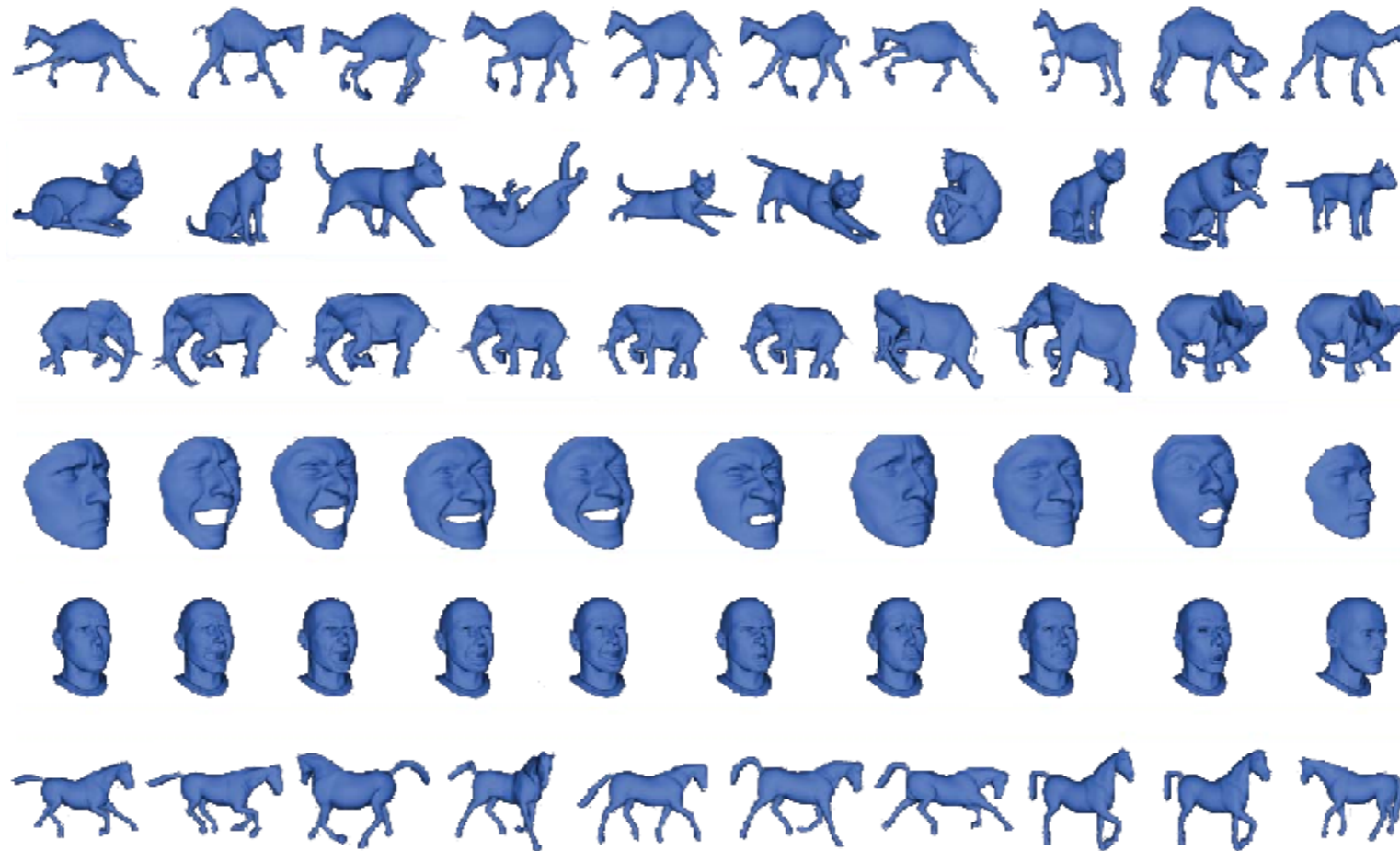
Rips-Based Signatures (continued)

Signatures of some elementary shapes (approximated from finite samples):



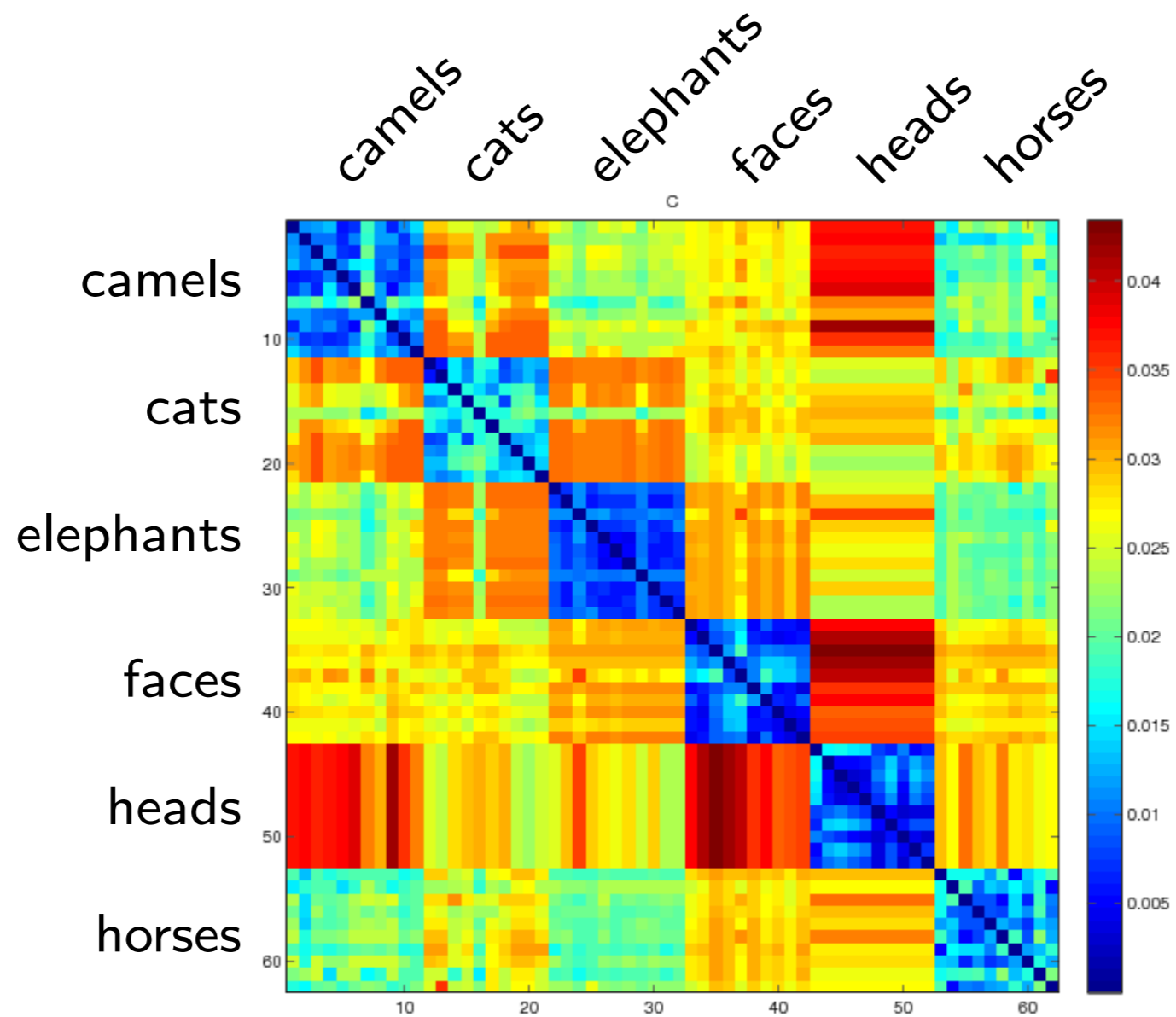
Rips-Based Signatures (continued)

Experimental results:



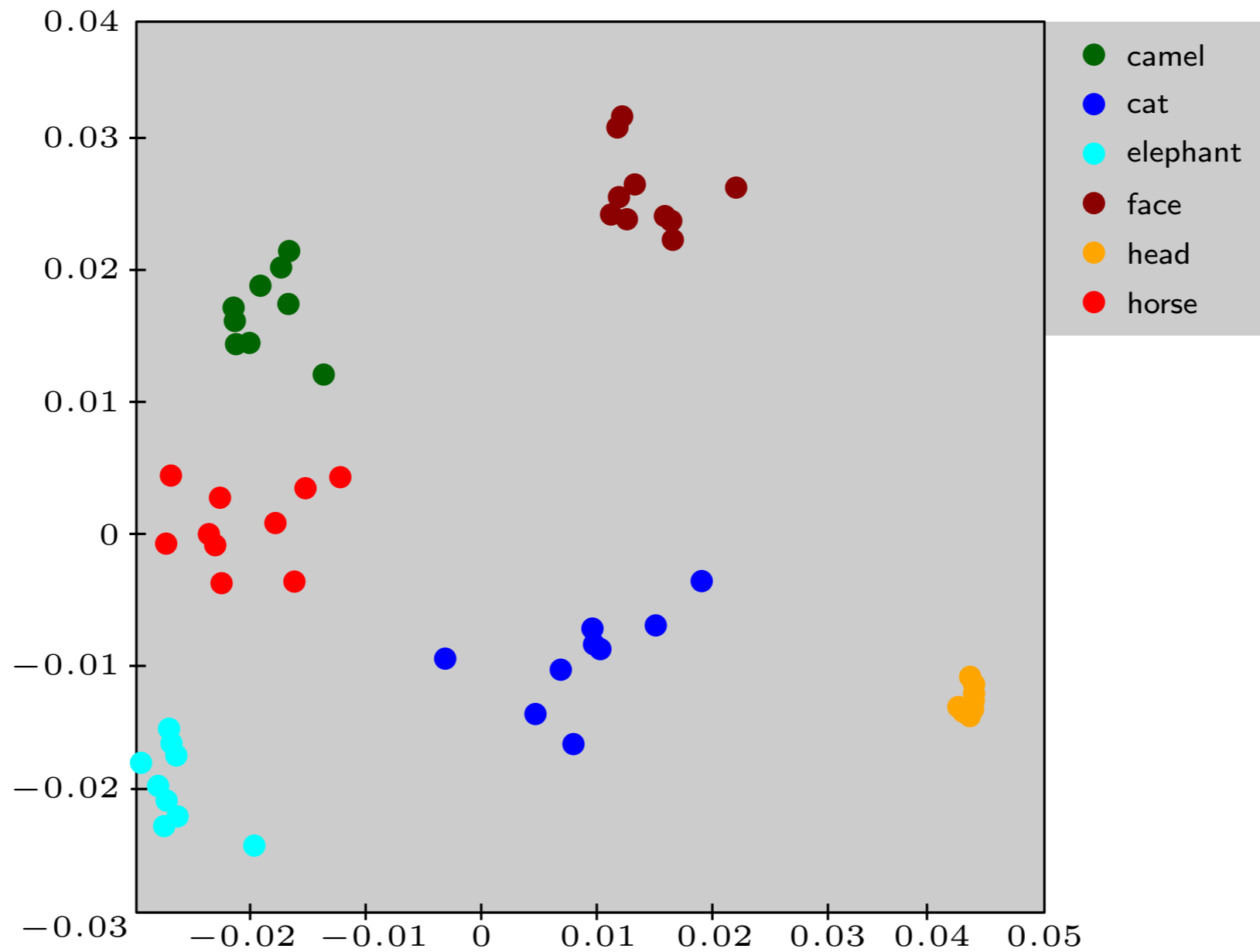
Rips-Based Signatures (continued)

Experimental results:



Rips-Based Signatures (continued)

Experimental results:



Function-Based Signatures

Input: a compact metric space (X, d_X) and a Lipschitz function $f : X \rightarrow \mathbb{R}$

Signature: $Dg f$

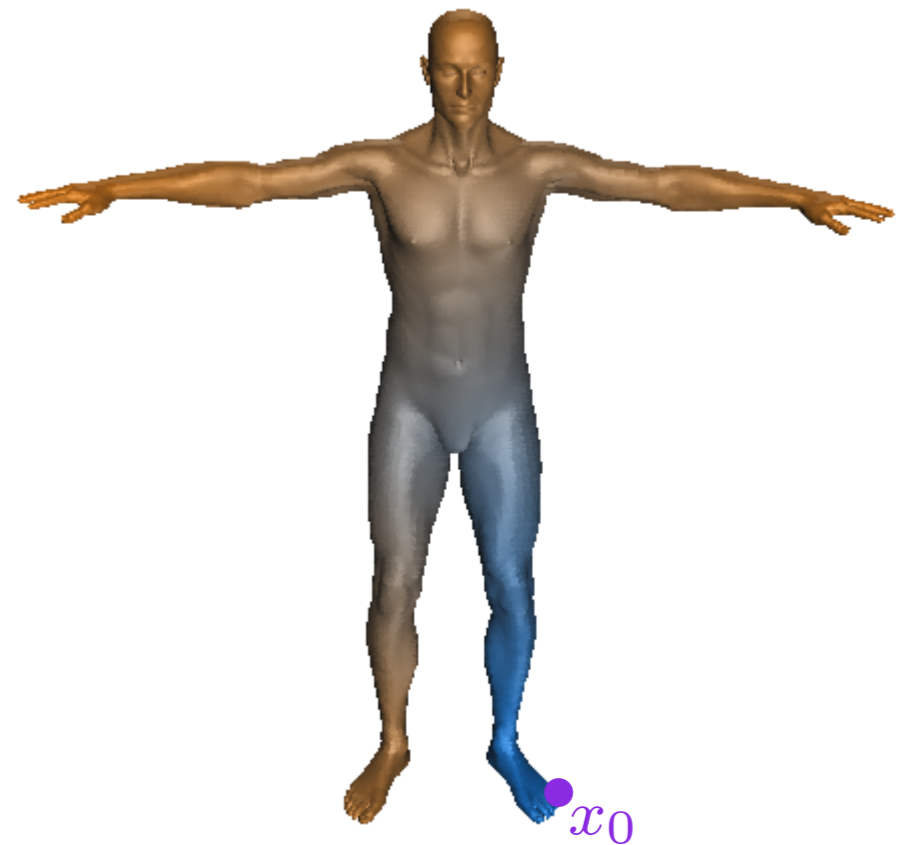
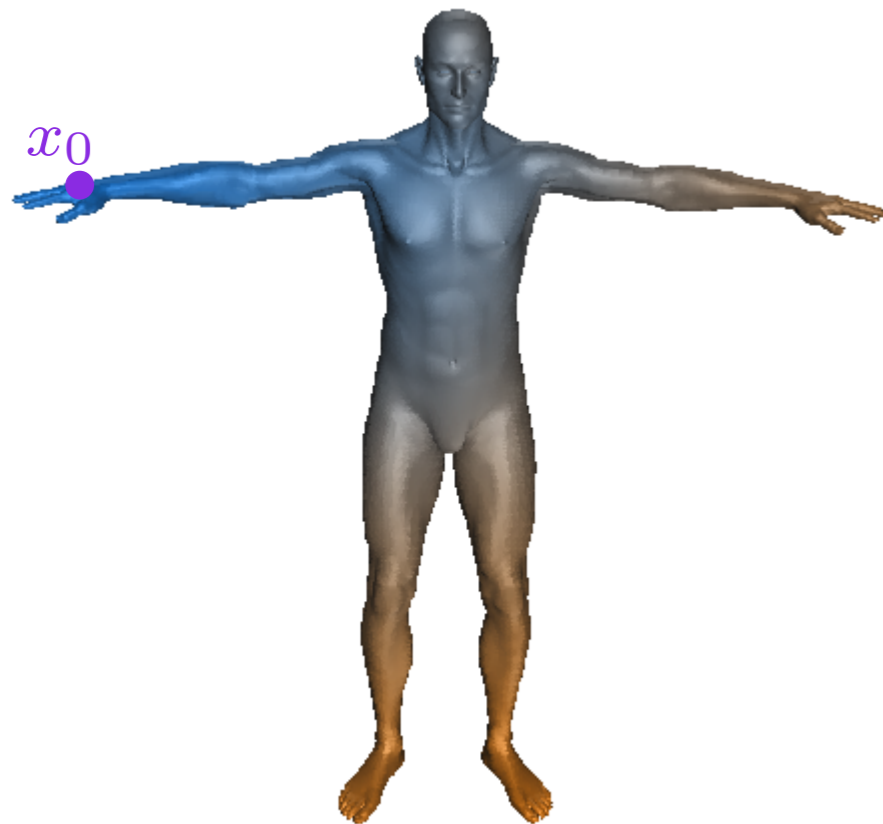
Function-Based Signatures

Input: a compact metric space (X, d_X) and a Lipschitz function $f : X \rightarrow \mathbb{R}$

Signature: $Dg f$

Examples:

- distance to a base point $x_0 \in X$: $f_{x_0}(x) = d_X(x, x_0)$ is 1-Lipschitz



Function-Based Signatures

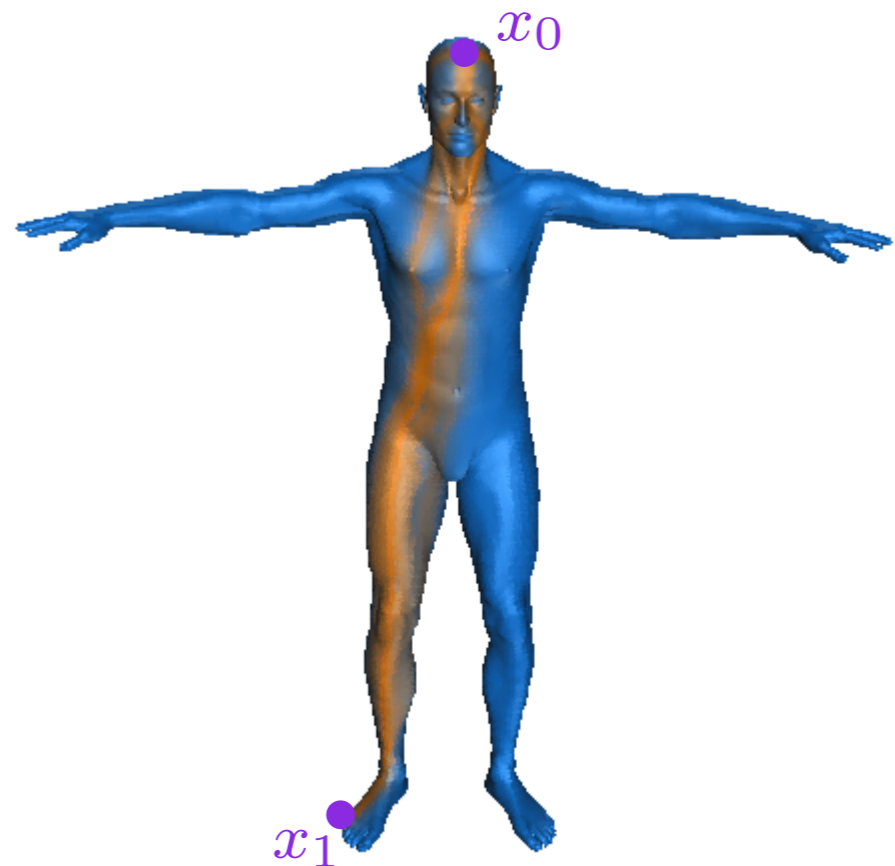
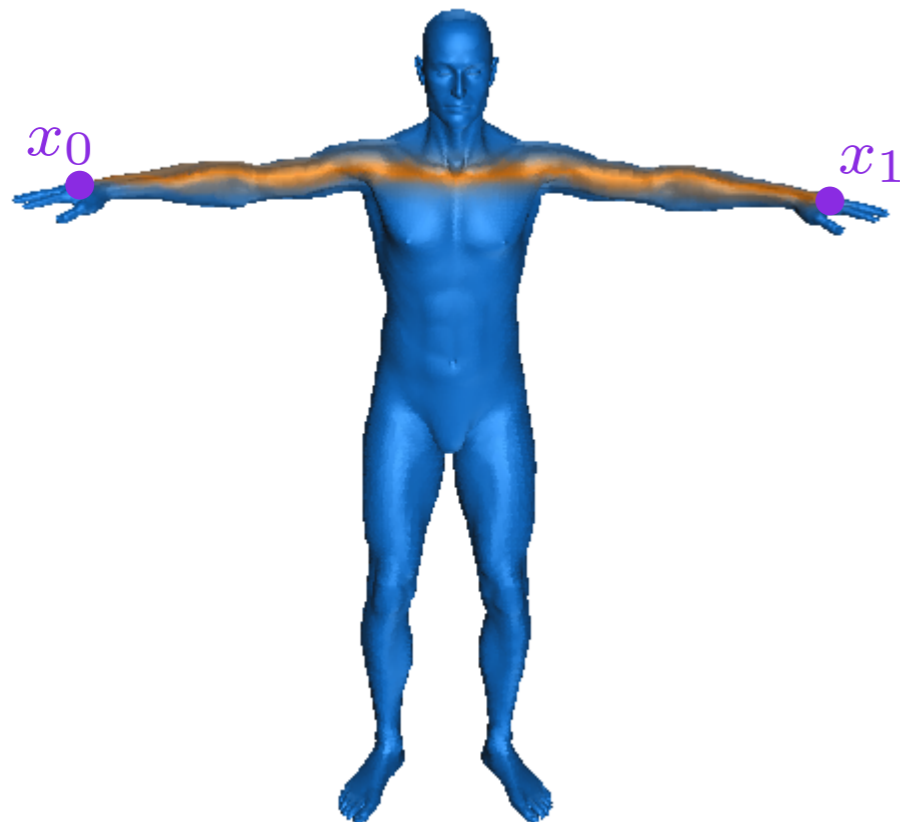
Input: a compact metric space (X, d_X) and a Lipschitz function $f : X \rightarrow \mathbb{R}$

Signature: $Dg f$

Examples:

- *fuzzy geodesic* [SCF'10] of a pair of base points $x_0, x_1 \in X$:

$$f_{x_0, x_1}(x) = \exp\left(-\frac{|d_X(x, x_0) + d_X(x, x_1) - d_X(x_0, x_1)|}{\sigma}\right) \text{ is } \frac{2}{\sigma}\text{-Lipschitz,}$$



Function-Based Signatures

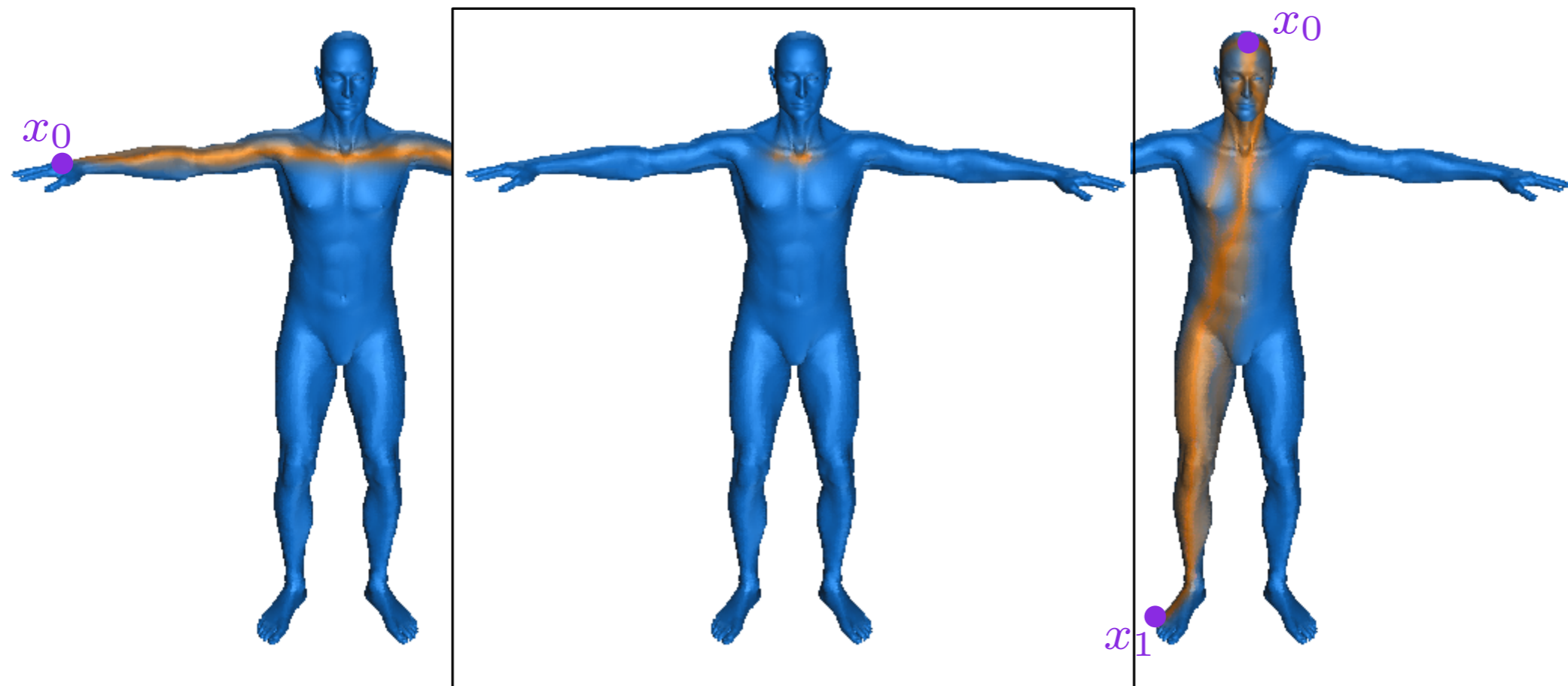
Input: a compact metric space (X, d_X) and a Lipschitz function $f : X \rightarrow \mathbb{R}$

Signature: $Dg f$

Examples:

- *intersection configuration* [SCF'10] of a quadruple of base points:

$f_{x_0, x_1, x_2, x_3}(x) = f_{x_0, x_1}(x) \cdot f_{x_2, x_3}(x)$ is $\frac{4}{\sigma}$ -Lipschitz.



Function-Based Signatures (continued)

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

$$d_B^\infty(\text{Dg } f, \text{Dg } g) \in O(c \text{dist}_m(C) + \text{dist}_f(C)).$$

Function-Based Signatures (continued)

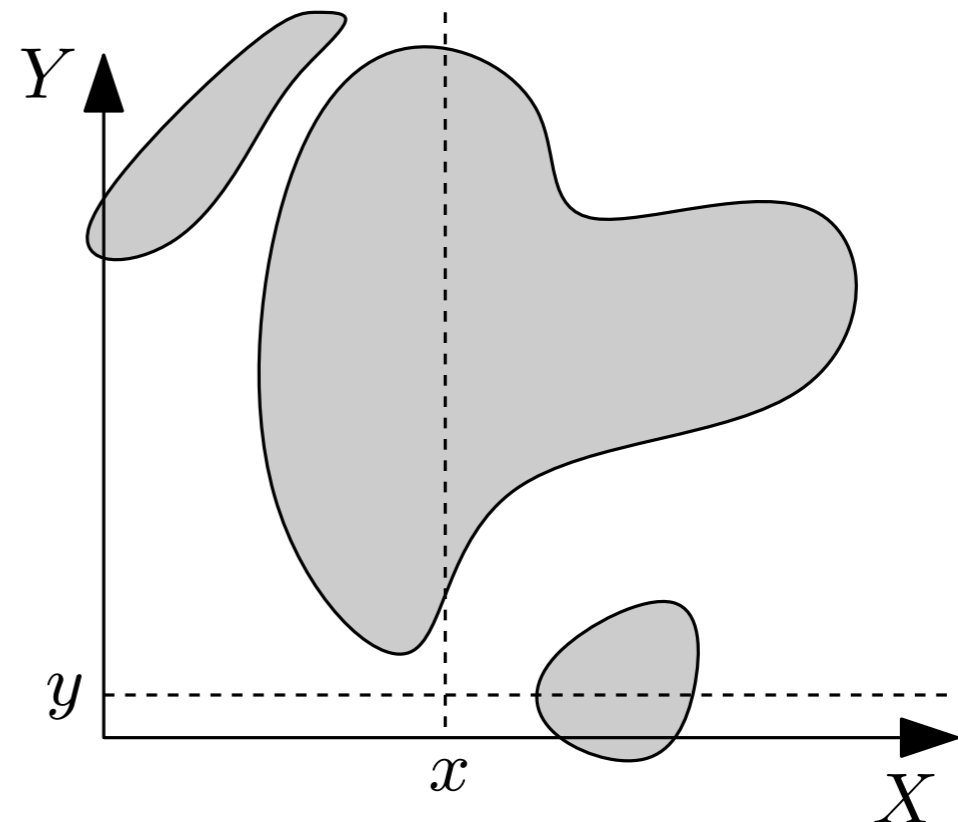
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Definitions:

- correspondence



Function-Based Signatures (continued)

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

$$d_B^\infty(\text{Dg } f, \text{Dg } g) \in O(c \text{dist}_m(C) + \text{dist}_f(C)).$$

Definitions:

- correspondence

- distortion

$$\left| \begin{array}{l} \text{dist}_m(C) = \sup_{(x,y),(x',y') \in C} |d_X(x, x') - d_Y(y, y')| \\ \text{dist}_f(C) = \sup_{(x,y) \in C} |f(x) - g(y)| \end{array} \right.$$

Function-Based Signatures (continued)

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

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Definitions:

- correspondence
- distortion
- Gromov-Hausdorff distance

$$d_{\text{GH}}(X, Y) = \frac{1}{2} \inf_{C \in \mathcal{C}(X, Y)} \text{dist}_m(C)$$

Function-Based Signatures (continued)

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

$$d_B^\infty(\text{Dg } f, \text{Dg } g) \in O(c \text{dist}_m(C) + \text{dist}_f(C)).$$

Note: this is a stability theorem for persistence diagrams

- improves over [CEH'05] (functions have different domains)
- improves over [dAFL'08] (domains are in different homeomorphism classes)
- relies on and is more specific than [CCGGGO'09]

Function-Based Signatures (continued)

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

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But it is not true in such generality:

- $d_B^\infty(\text{Dg } f, \text{Dg } g) < \infty \Rightarrow (X, d_X)$ and (Y, d_Y) are homologically equivalent
- $\text{dist}_m(C)$ and $\text{dist}_f(C)$ are finite regardless of homological types of X, Y

Function-Based Signatures (continued)

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

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→ Restrict the focus to a class of *sufficiently regular* metric spaces

Function-Based Signatures (continued)

Obtained stability result:

length spaces of curvature bounded above

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact ~~metric spaces~~ equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$,

$$\begin{aligned} d_B^\infty(\text{Dg } f, \text{Dg } g) &\in \mathcal{O}(\cancel{c \text{dist}_m(C)} + \text{dist}_f(C)). \\ &\leq 19c \text{dist}_m(C) + \text{dist}_f(C) \end{aligned}$$

Function-Based Signatures (continued)

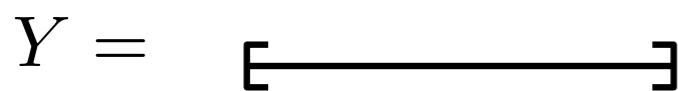
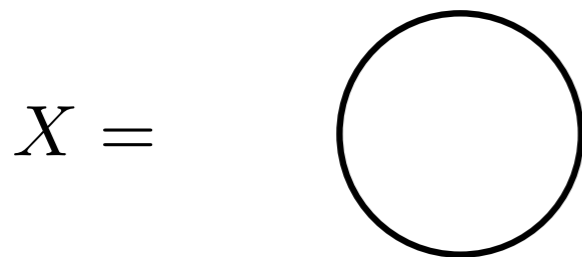
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Prerequisite: $d_{\text{GH}}(X, Y) < \frac{1}{20} \min\{\varrho(X), \varrho(Y)\}$



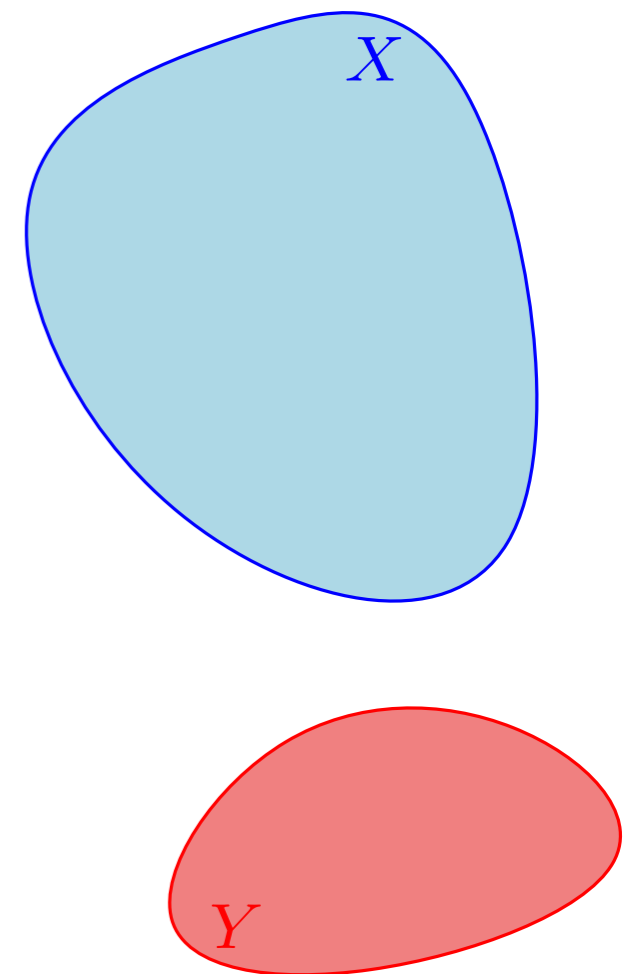
$$d_{\text{GH}}(X, Y) < \infty = \varrho(Y)$$

$$d_B^\infty(\text{Dg } f, \text{Dg } g) = \infty$$

Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(\text{Dg } f, \text{Dg } g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

Proof: reduction to *Scalar Fields Analysis from Point Cloud Data* [CGOS'09]:



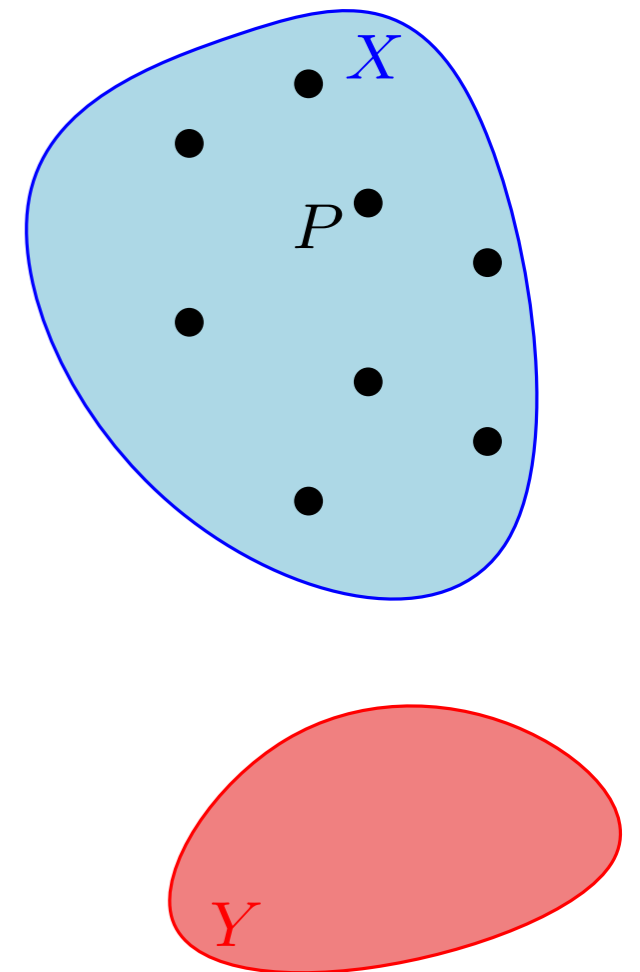
Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(Dg f, Dg g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

Proof: reduction to *Scalar Fields Analysis from Point Cloud Data* [CGOS'09]:

Given any positive $\varepsilon < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\} - \text{dist}_m(C)$,

- take a finite ε -sample P of X ($P \subseteq X$)
- equip it with the induced metric $d_P = d_X|_{P \times P}$
- equip it with the restriction $h = f|_P$



Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(\text{Dg } f, \text{Dg } g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

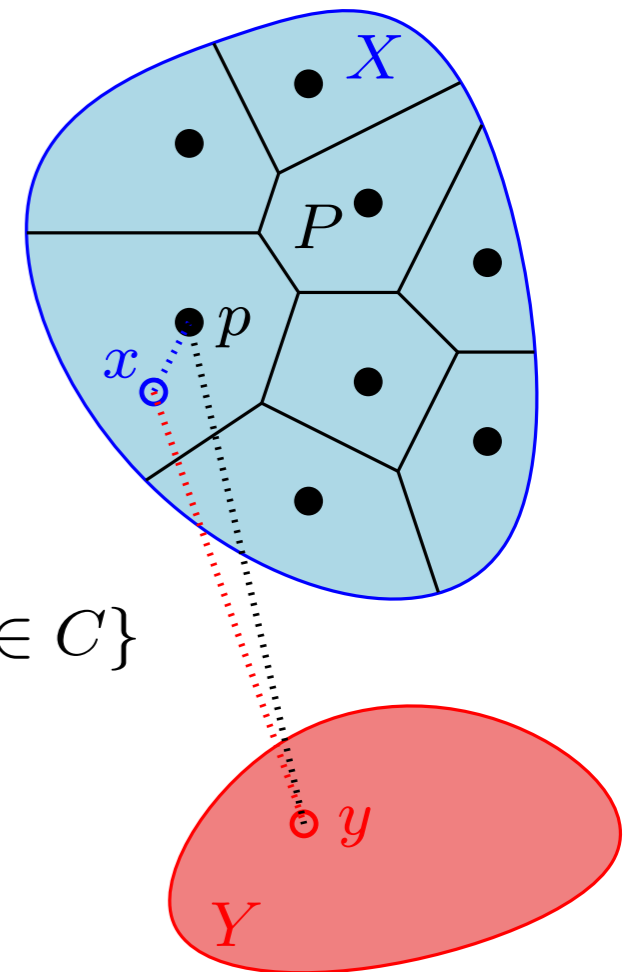
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$$C_{PX} = \{(p, x) \in P \times X : d_X(x, p) = \min_{q \in P} d_X(x, q)\}$$

$$C_{PY} = \{(p, y) \in P \times Y : \exists x \in X \text{ s.t. } (p, x) \in C_{PX} \text{ and } (x, q) \in C\}$$



Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(Dg f, Dg g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

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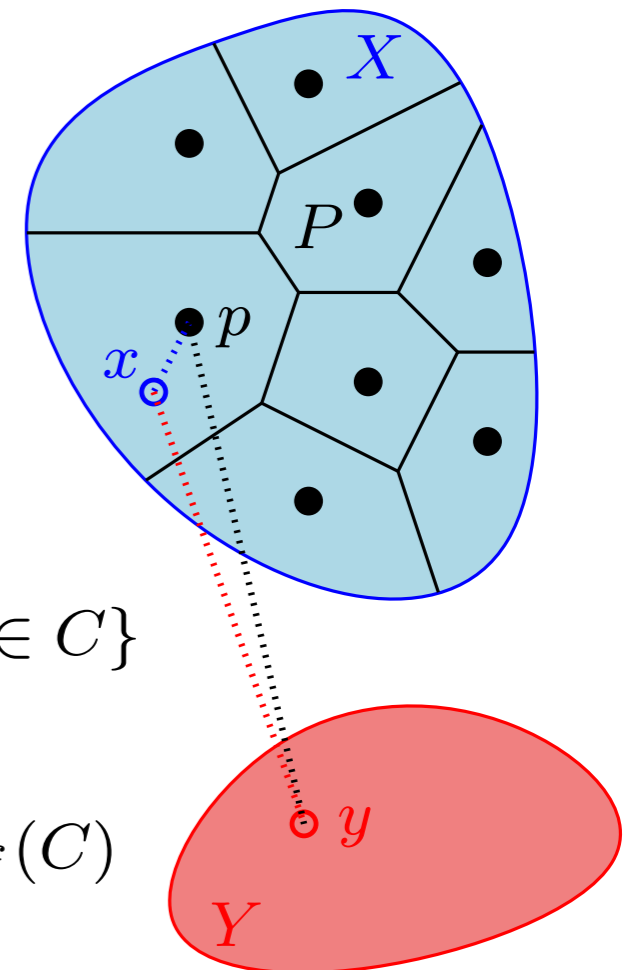
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$$\rightarrow \left| \begin{array}{l} \text{dist}_m(C_{PX}) \leq 2\varepsilon \text{ and } \text{dist}_f(C_{PX}) = c\varepsilon \\ \text{dist}_m(C_{PY}) \leq 2\varepsilon + \text{dist}_m(C) \text{ and } \text{dist}_f(C_{PY}) \leq c\varepsilon + \text{dist}_f(C) \end{array} \right.$$

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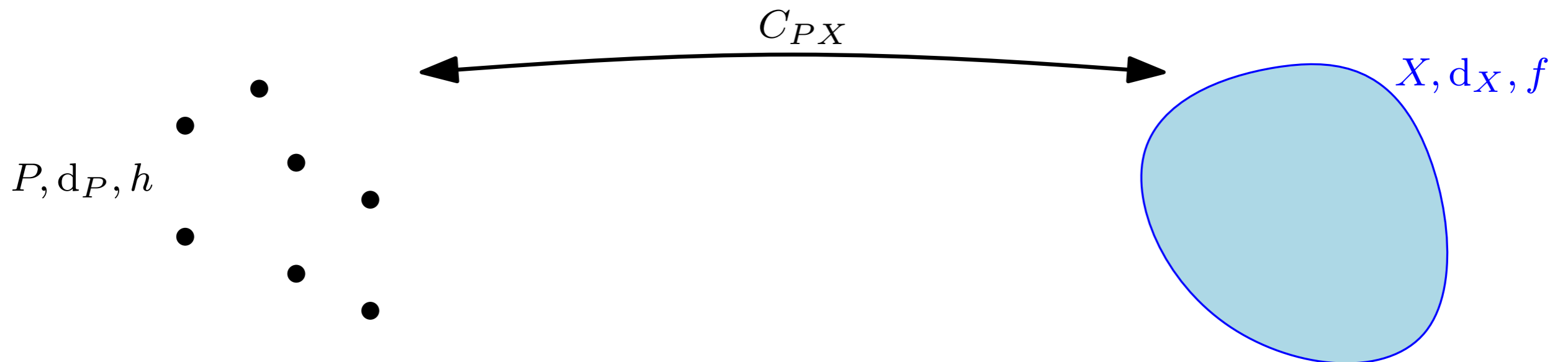
→ goal: approximate persistence diagram from GH-close finite metric space



Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(\text{Dg } f, \text{Dg } g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

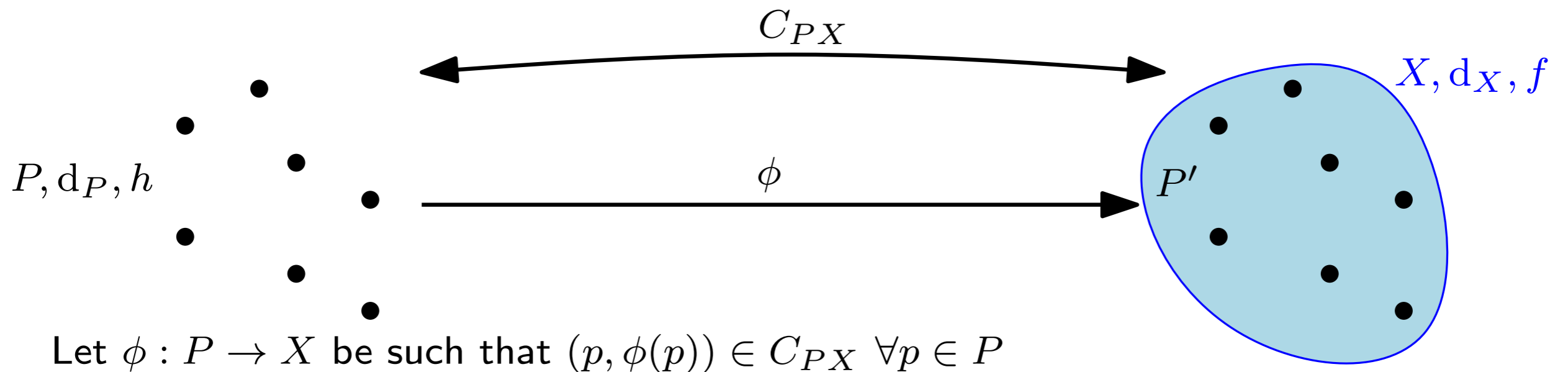
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Function-Based Signatures (continued)

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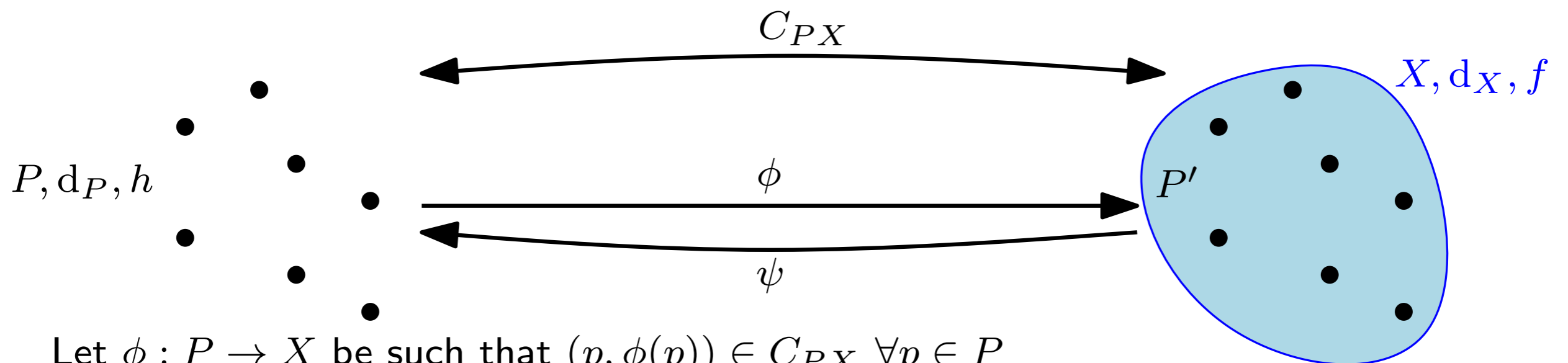
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Function-Based Signatures (continued)

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Proof: reduction to *Scalar Fields Analysis from Point Cloud Data* [CGOS'09]:



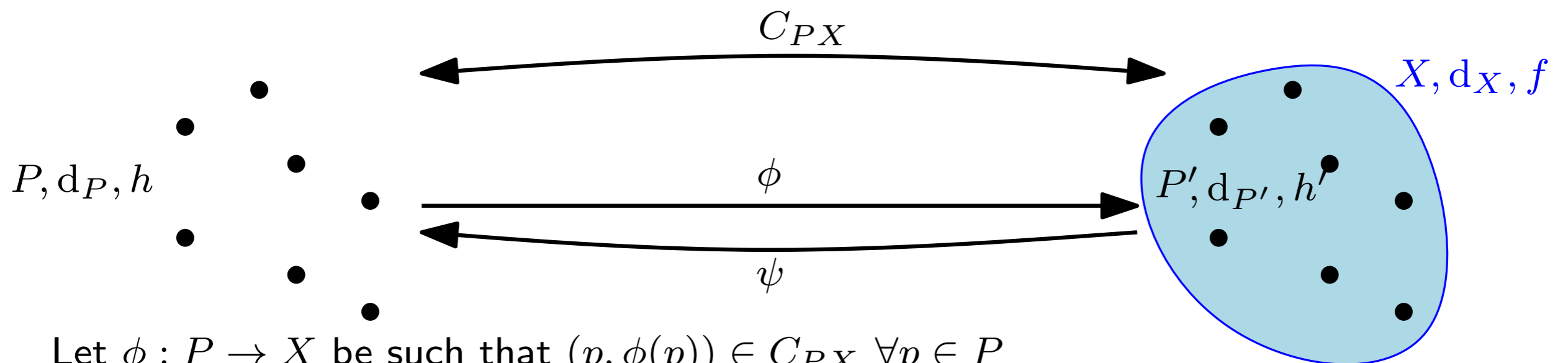
Let $\phi : P \rightarrow X$ be such that $(p, \phi(p)) \in C_{PX} \forall p \in P$

Assume wlog that ϕ is **injective** and let $\psi : X \rightarrow P$ be a left inverse

Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(\text{Dg } f, \text{Dg } g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

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Equip $P' = \phi(P)$ with $d_{P'} = d_P(\psi(\cdot), \psi(\cdot))$ and $h' = h \circ \psi$

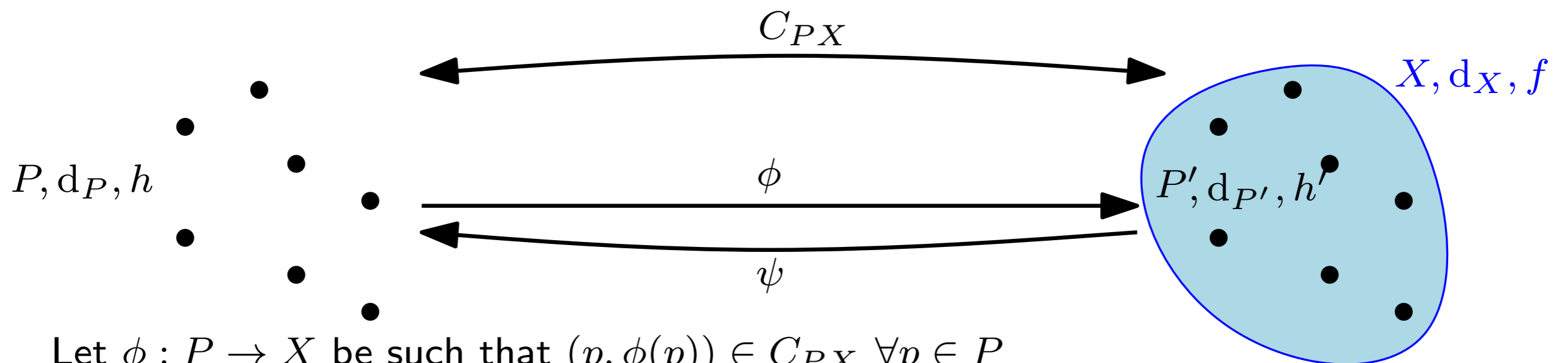
$\rightarrow d_H(P', X) \leq \text{dist}_m(C)$

$\|h' - f|_{P'}\|_\infty \leq \text{dist}_f(C)$ and $\|d_{P'} - d_X|_{P' \times P'}\|_\infty \leq \text{dist}_m(C)$

Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(\text{Dg } f, \text{Dg } g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

Proof: reduction to *Scalar Fields Analysis from Point Cloud Data* [CGOS'09]:



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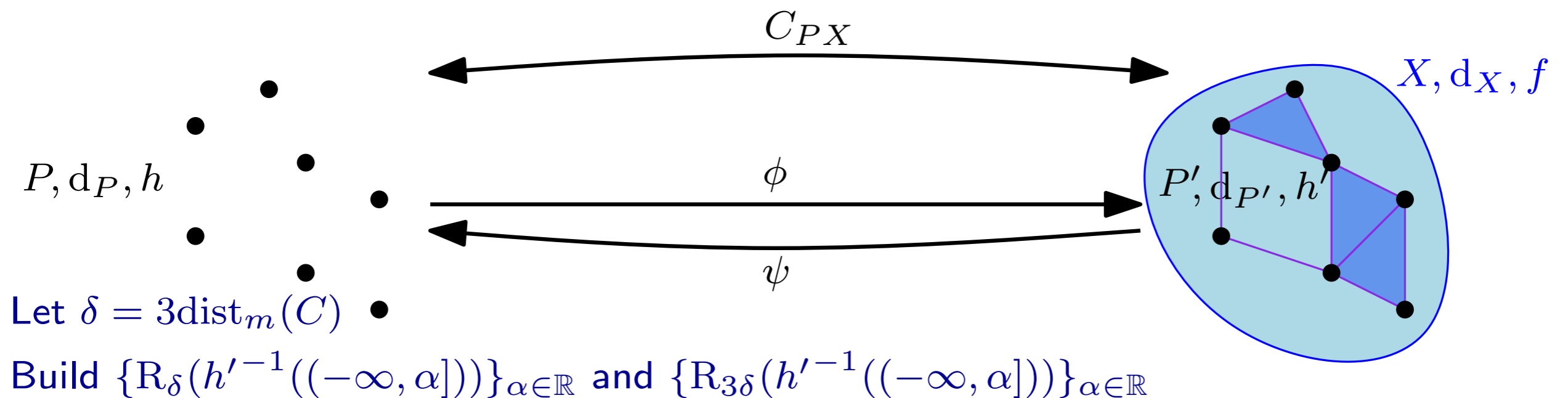
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$\rightarrow \left\{ \begin{array}{l} d_H(P', X) \leq \text{dist}_m(C) \\ \|h' - f|_{P'}\|_\infty \leq \text{dist}_f(C) \text{ and } \|d_{P'} - d_X|_{P' \times P'}\|_\infty \leq \text{dist}_m(C) \end{array} \right.$ scenario considered in [CGOS'09] \square

Function-Based Signatures (continued)

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact Riemannian manifolds equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(\text{Dg } f, \text{Dg } g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

Proof: reduction to *Scalar Fields Analysis from Point Cloud Data* [CGOS'09]:

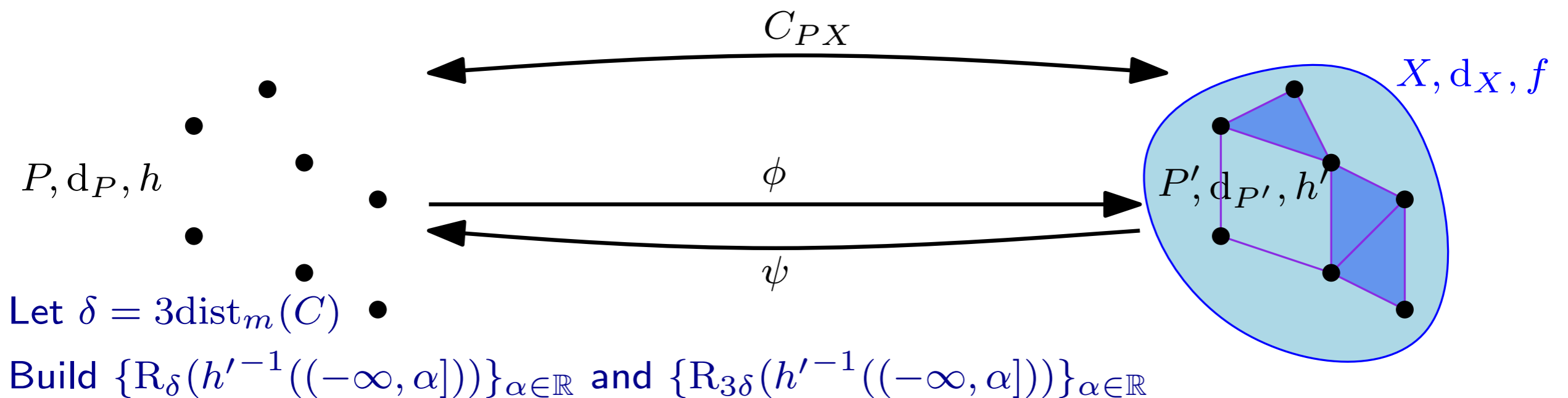


$\rightarrow \left\{ \begin{array}{l} d_H(P', X) \leq \text{dist}_m(C) \\ \|h' - f|_{P'}\|_\infty \leq \text{dist}_f(C) \text{ and } \|d_{P'} - d_X|_{P' \times P'}\|_\infty \leq \text{dist}_m(C) \end{array} \right.$ scenario considered in [CGOS'09] \square

Function-Based Signatures (continued)

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Proof: reduction to *Scalar Fields Analysis from Point Cloud Data* [CGOS'09]:



Thm: $d_B^\infty(\text{Dg } f, \text{Dg } \{\text{Im } H_*(R_\delta(h'^{-1}((-\infty, \alpha]))) \rightarrow H_*(R_{3\delta}(h'^{-1}((-\infty, \alpha])))\}_{\alpha \in \mathbb{R}})$
 $\leq 10c \text{dist}_m(C) + \text{dist}_f(C)$

$\rightarrow \left\{ \begin{array}{l} d_H(P', X) \leq \text{dist}_m(C) \\ \|h' - f|_{P'}\|_\infty \leq \text{dist}_f(C) \text{ and } \|d_{P'} - d_X|_{P' \times P'}\|_\infty \leq \text{dist}_m(C) \end{array} \right.$ scenario considered in [CGOS'09] □

Function-Based Signatures (continued)

Computing (approximating) the signatures in practice:

- when a triangulation of the manifold X is given:
 - replace f by its PL interpolation \hat{f} over the triangulation
 - compute $Dg \hat{f}$
 - $d_B^\infty(Dg f, Dg \hat{f})$ is controlled by the stability theorem for PDs [CEH'05]

Function-Based Signatures (continued)

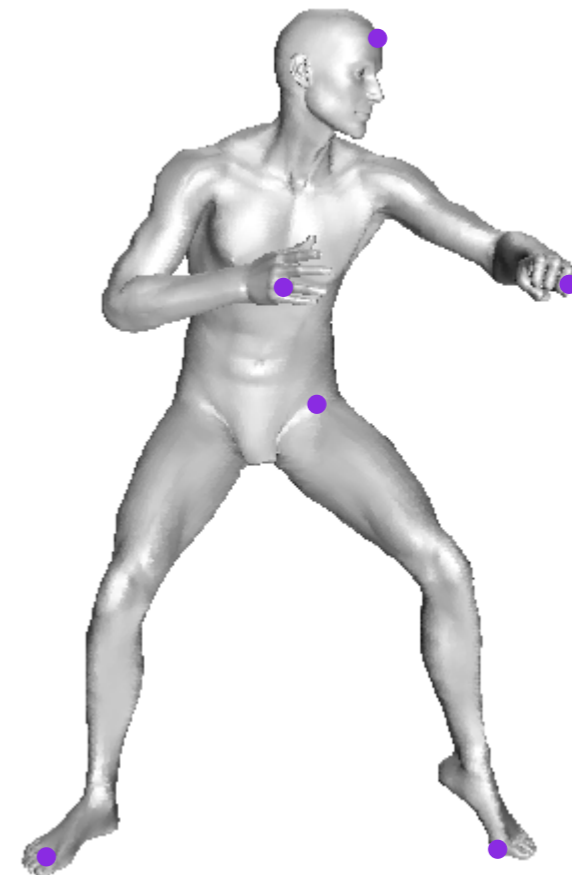
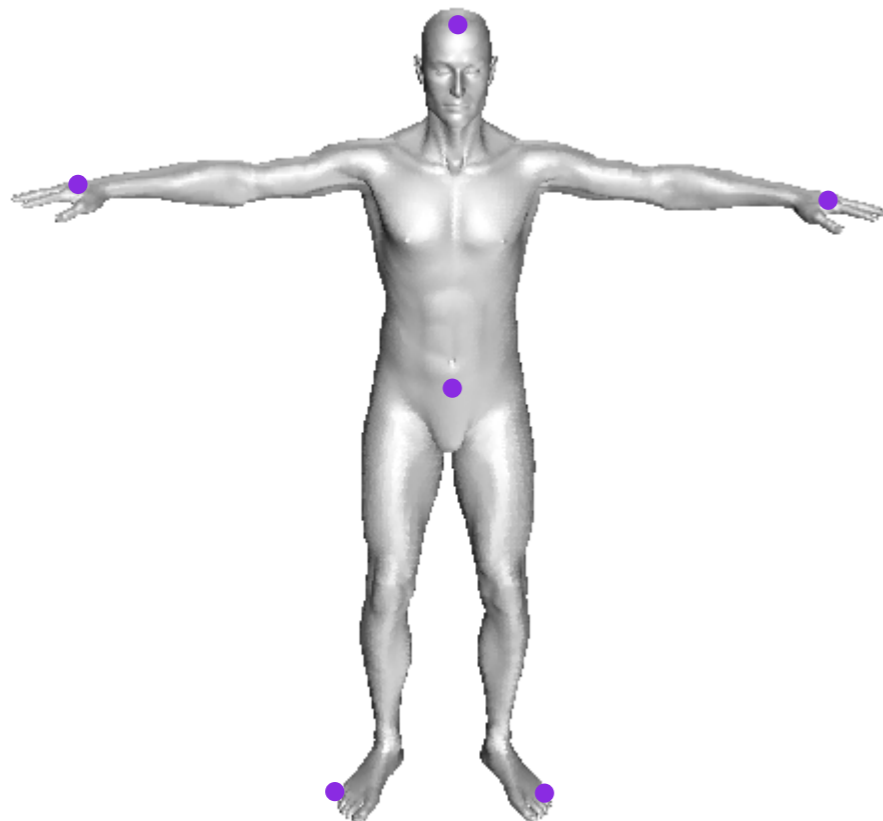
Computing (approximating) the signatures in practice:

- when a triangulation of the manifold X is given:
 - replace f by its PL interpolation \hat{f} over the triangulation
 - compute $Dg \hat{f}$
 - $d_B^\infty(Dg f, Dg \hat{f})$ is controlled by the stability theorem for PDs [CEH'05]
- when a finite approximation (P, d_P, g) of (X, d_X, f) is given:
 - choose a neighborhood parameter $\delta > 0$
 - build the filtrations $\{R_\delta(g^{-1}((-\infty, \alpha]))\}_{\alpha \in \mathbb{R}}$ and $\{R_{3\delta}(g^{-1}((-\infty, \alpha]))\}_{\alpha \in \mathbb{R}}$
 - compute the PD of the image persistence module induced by inclusions:
$$\{\text{Im } H_*(R_\delta(g^{-1}((-\infty, \alpha]))) \rightarrow H_*(R_{3\delta}(g^{-1}((-\infty, \alpha])))\}_{\alpha \in \mathbb{R}}$$
 - bottleneck distance to $Dg f$ is controlled by the results of [CGOS'09]

Function-Based Signatures (continued)

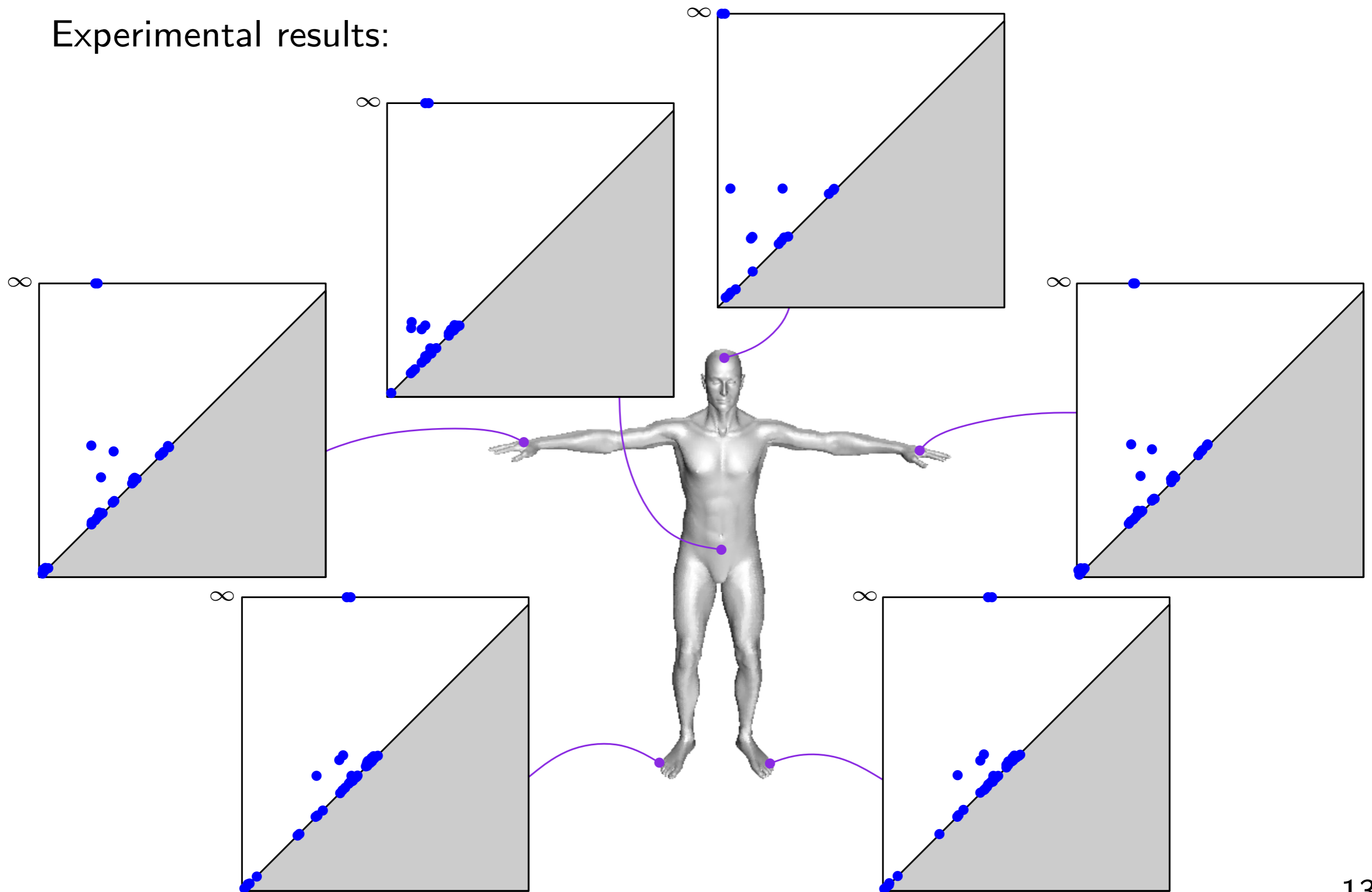
Experimental results:

- input: shapes from the TOSCA database, in *mesh* form
- select a few base points by hand on each shape
- approximate geodesic distances to base points using the 1-skeleton graph
- use the PDs of the PL interpolations over the meshes as signatures



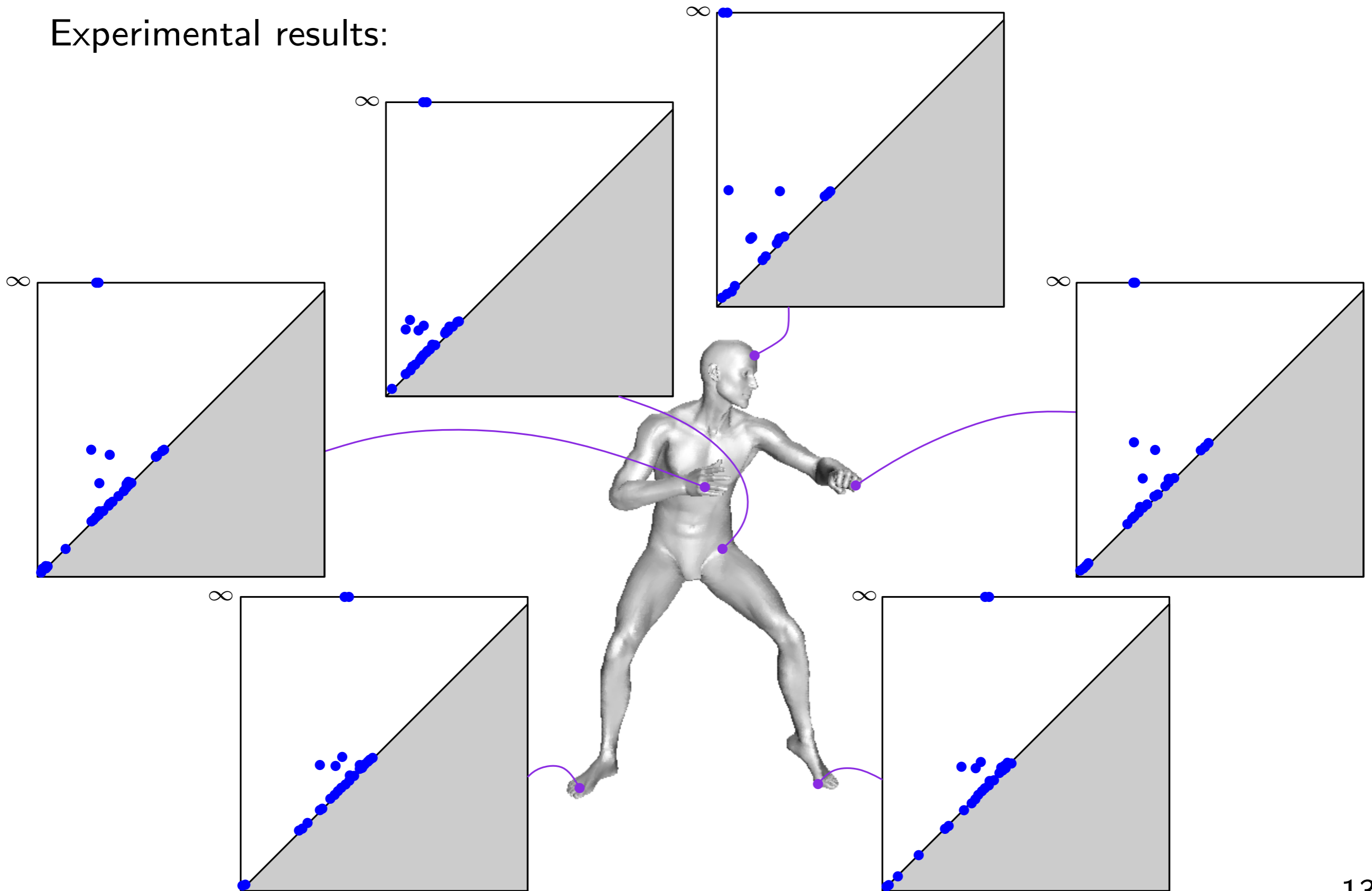
Function-Based Signatures (continued)

Experimental results:



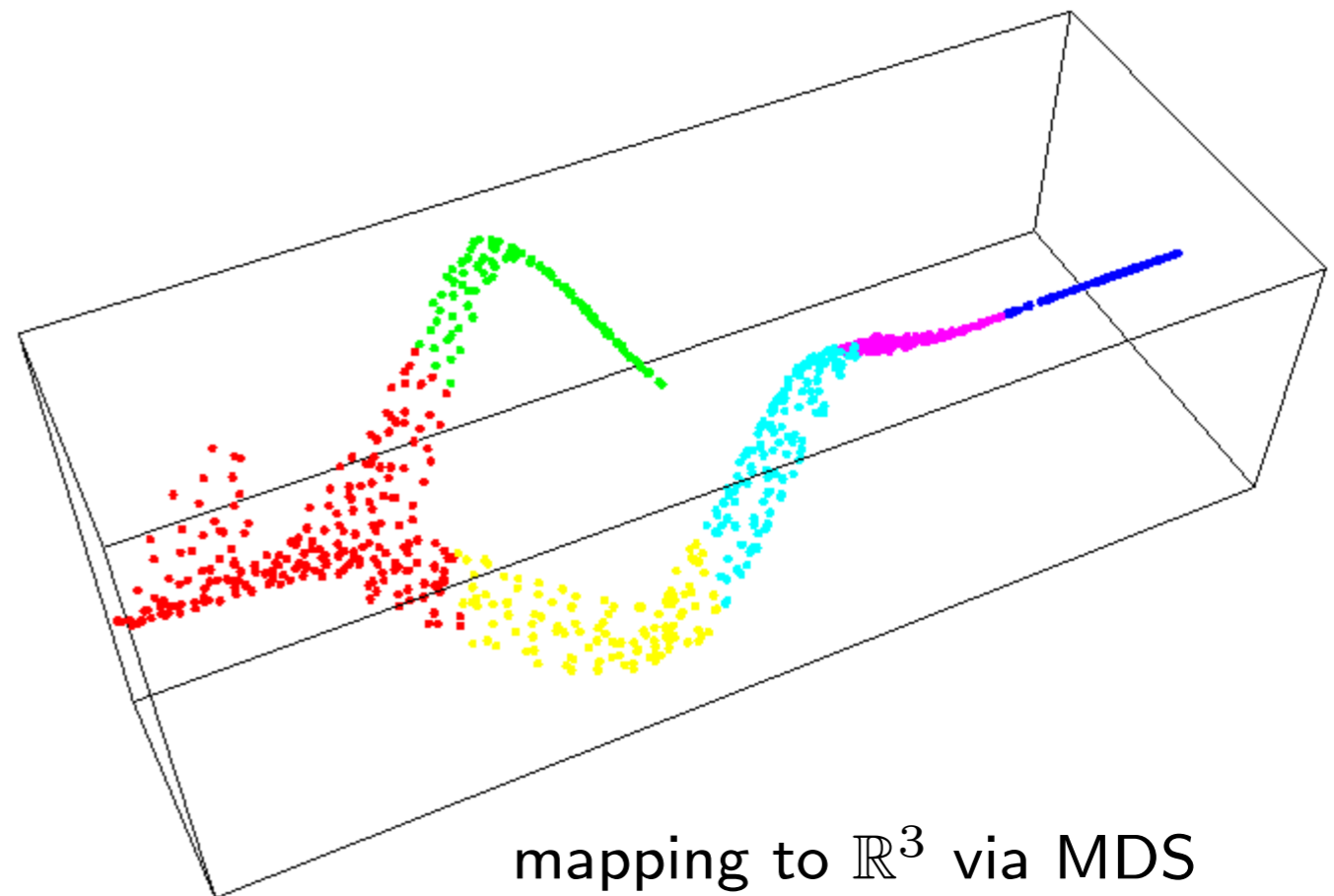
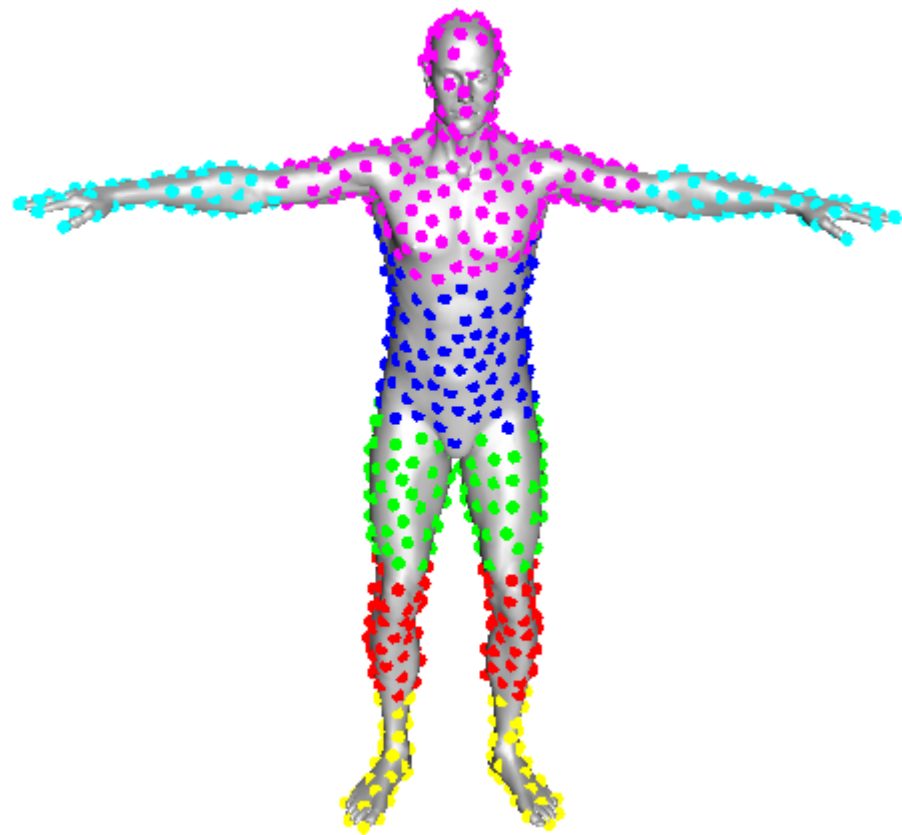
Function-Based Signatures (continued)

Experimental results:



Function-Based Signatures (continued)

Experimental results:

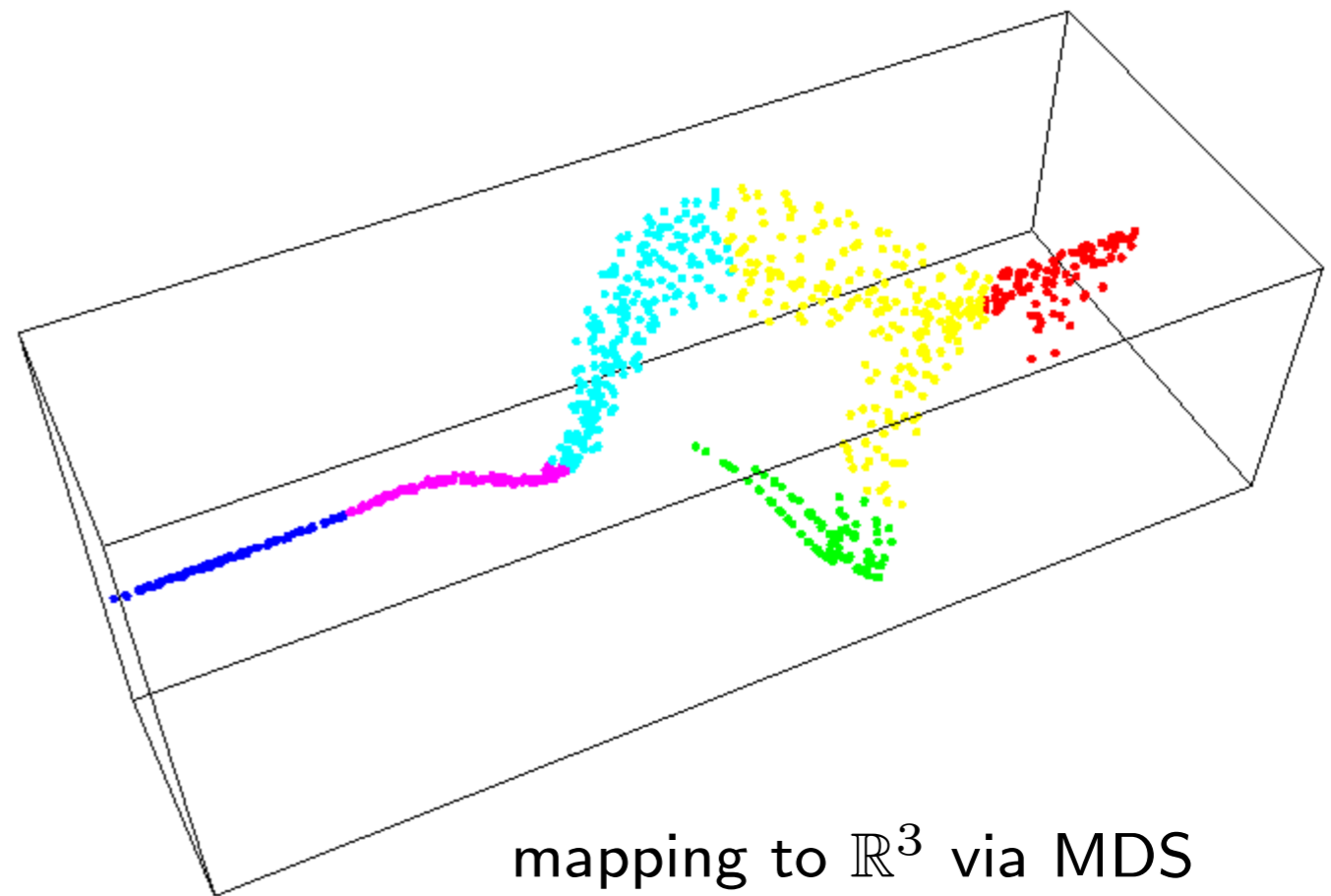
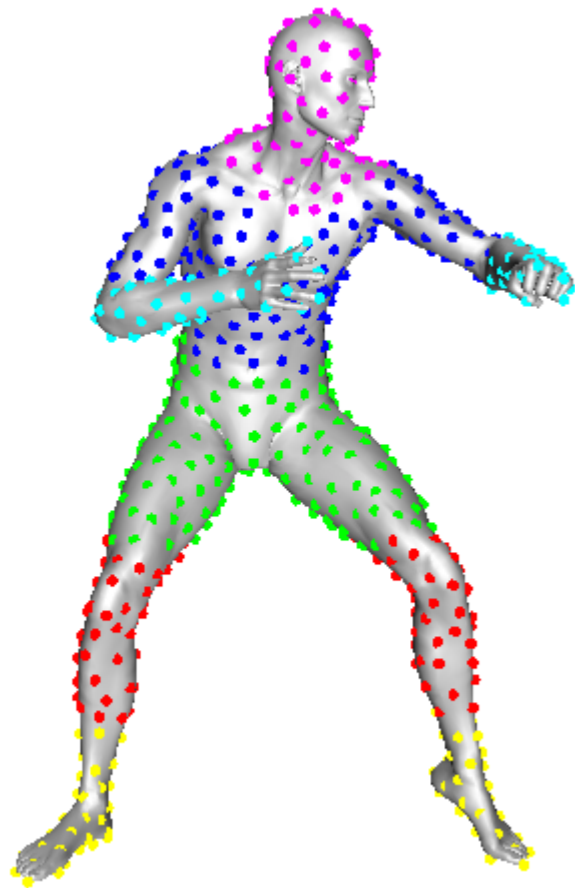


mapping to \mathbb{R}^3 via MDS

k -means in \mathbb{R}^3

Function-Based Signatures (continued)

Experimental results:



mapping to \mathbb{R}^3 via MDS

k -means in \mathbb{R}^3

Conclusion

- Two families of signatures: Rips-based and function-based
- Flexibility via choice of metric and/or function

2-parameters filtration \rightarrow relate the 2 parameters by a linear relation, e.g. α

\rightarrow 2-parameter family of filtrations

Q Consider bi-filtration directly?

